

**REV. May 2018** 



(VL-EPMe-42)

Intel® Core™-based Single Board Computer with Dual Ethernet, Video, USB, SATA, Serial I/O, Digital I/O, Trusted Platform Module security, Counter/Timers, Mini PCIe, mSATA, SPX, and PCIe/104™ OneBank™ Interface









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## **Product Release Notes**

Release 1.3- Updated Uartmode1 – Uart Mode Register #1 section

Release 1.2- Added descriptions to the FPGA table

Release 1.1- Updated Processor Wake# section

Release 1.0- Initial Production Draft

## **Support**

The EPMe-42 support page contains additional information and resources for this product including:

- Reference Manual (PDF format)
- Operating system information and software drivers
- Data sheets and manufacturers' links for chips used in this product
- BIOS information and upgrades
- Utility routines and benchmark software

The VersaTech KnowledgeBase is an invaluable resource for resolving technical issues with your VersaLogic product.

VersaTech KnowledgeBase

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Overview

This document provides information for users requiring register-level information for developing applications as it relates the FPGA functionality with the VL-EPMe-42.

## **Related Documents**

The following documents available are on the EPMe-42 Product Support Web Page:

- *EPMe-42 Hardware Reference Manual* provides information on the board's hardware features including connectors and all interfaces.
- *EPMe-42 BIOS Reference Manual* provides information on accessing and configuring settings in the BIOS Setup utility. All BIOS menus, submenus, and configuration options are described.

This document is available through the software page:

 <u>VersaAPI Installation and Reference Guide</u> – describes the shared library of API calls for reading and controlling on-board devices on certain VersaLogic products.

# **System Resources and Maps**

## **Memory Map**

**Table 1: Memory Map** 

Address Range	Description
00000h – 9FFFFh	Legacy system (DOS) area
A0000h – B7FFFh	ISA memory area (VGA frame buffer is not accessible)
B8000h – BFFFFh	Text mode buffer
C0000h - CFFFFh	Video BIOS area
D0000h – DFFFFh	PCI ROM expansion area
E0000h – FFFFFh	Legacy BIOS (reserved)

# **Interrupts**

The LPC SERIRQ is used for interrupt interface to the Kaby Lake SoC.

Each of the following devices can have an IRQ interrupt assigned to it and each with an interrupt enable control for IRQ3, IRQ4, IRQ5, IRQ6, IRQ7, IRQ9, IRQ10, and IRQ11:

- 8254 timers (with three interrupt status bits)
- 8 AUX GPIOs (with one interrupt status bit)
- COM 1 UART (with 16550 interrupt status bits)
- COM 2 UART (with 16550 interrupt status bits)
- Watchdog timer (one interrupt status bit)
- SPX expansion interface (interrupt status is determined by the devices on this interface). The interface supports two interrupts.
- Thermal event and battery-low interrupts

**Note:** The EPMe-42 also has two COM ports (COM3, COM4) that are supported by the HSUARTs in the processor.

The FPGA supports 11 interrupts via the LPC SERIRQ interface: IRQ3, IRQ4, IRQ5, IRQ6, IRQ7, IRQ9, IRQ10, IRQ11, IRQ12, IRQ14, and IRQ15. There is an interrupt enable control for each and by default they are all disabled.

Common interrupts can be assigned to multiple devices (this is common on UARTs being handled by a common ISR).

Interrupt status bits for everything except the UARTs will "stick" and are cleared by a "write-one" to a status register bit. The 16550 UART interrupts behave as defined for the 16550 registers and are a pass-through to the LPC SERIRQ.

Per the VersaAPI standard, anytime an interrupt on the SERIRQ is enabled, the slot becomes active. All interrupts in the SERIRQ are high-true so when the slot becomes active, the slot will be low when there is no interrupt and high when there is an interrupt.

Table 2: I/O Map

I/O Address Range	Device/Owner
2F8h – 2FFh	COM2 serial port default
3B0h – 3DFh	Legacy VGA registers
3F8h – 3FFh	COM1 serial port default
400h – 47Fh	ACPI / Power management (reserved)
500h – 5FFh	PCH GPIO (reserved)
C80h – CBBh	EPMe-42 FPGA Board Control Registers
CBCh – CBFh	EPMe-42 FPGA 8254 Timer Registers

# **FPGA Registers**

# **FPGA I/O Space**

The FPGA is mapped into I/O space on the LPC bus. The address range is mapped into 64 byte I/O window.

- FPGA access: LPC I/O space
- FPGA access size: All 8-bit byte accesses (16-bit like registers are aligned on 16-bit word boundaries to make word access possible in software but the LPC bus still splits the accesses into two 8-bit accesses)
- FPGA address range: 0xC80 to 0xCBF (64-byte window)

The three 8254 timers only require four bytes of addressing and are located at the end of the 64-byte I/O block. The only requirement is that the base address must be aligned on a 4-byte block. Table 4 lists the FPGA's I/O map.

Table 3: FPGA I/O Map

Address Range	Device	Size		
0xC80 - 0xCBB	FPGA registers	60 bytes		
0xCBC - 0xCBF	8254 timer address registers	4 bytes		

# **FPGA Register Map**

	Register Access Key								
R/W	Read/Write								
RO	Read-only (status or reserved)								
R/WC	Read-status/Write-1-to-Clear								
WO	Write-Only								
ROC	Read-Only and clear-to-0 after reading								
RSVD	Reserved. Only write 0 to this bit; ignore all read values.								

	Reset Status Key								
POR	Power-on reset (only resets one time when input power comes on)								
Platform	Resets prior to the processor entering the S0 power state (that is, at power-o and in sleep states)								
resetSX	<ul> <li>If AUX_PSEN is a '0' in MISCSR1 (default setting), then this is the same as the Platform reset.</li> <li>If SUX_PSEN is a programmed to a '1', then it is the same as the Power-On Reset (POR).</li> </ul>								
n/a	Reset doesn't apply to status or reserved registers								

I/O Address	Offset	Reset	D7	D6	D5	D4	D3	D2	D1	D0	Description	
C80	0	Platform	PLED					PCR - Product Code & PLED				
C81	1	n/a			REV_LEVEL			EXTEMP	CUSTOM	BETA	PSR - Rev, Ext Tmp, Custom, Beta	
C82	2	Platform	BIOS_JMP	BIOS_OR	BIOS_SEL	LED_DEBUG	WORKVER	0	GPI_JMP	0	SCR - BIOS & Jumper status	
C83	3	Platform	IRQEN	IRQSEL2	IRQSEL1	IRQSEL0	0	IMASK_TC5	IMASK_TC4	IMASK_TC3	TICR - Timer Interrupt Control Register	
C84	4	Platform	INTRTEST	TMRTEST	TMRIN4	TMRIN3	0	ISTAT_TC5	ISTAT_TC4	ISTAT_TC3	TISR - Interrupt Status Reg (& timer debug test)	
C85	5	Platform	TIM5GATE	TIM4GATE	TIM3GATE	TM45MODE	TM4CLKSEL	TM3CLKSEL	TMROCTST	TMRFULL	TCR - Timer Control Reg (also see AUX GPIO Secondary Modes later)	
C86	6	n/a	0	0	0	0	0	0	0	0	Reserved	
C87	7	n/a	0	0	0	0	0	0	0	0	Reserved	
C88	8	Platform	CPOL	СРНА	SPILEN1	SPILEN0	MAN_SS	SS2	SS1	SS0	SPICONTROL (traditional location for SPX regs)	
C89	9	Platform	IRQSEL1	IRQSEL0	SPICLK1	SPICLK0	HW_IRQ_EN	LSBIT_1ST	HW_INT	BUSY	SPISTATUS	
C8A	Α	Platform	msb			<====	=====>	Isb	SPIDATA0 Least Significant Byte			
C8B	В	Platform	msb			<====	=====>			Isb	SPIDATA1	

C8C	С	Platform	msb		<======>								
C8D	D	Platform	msb		<=====>								
C8E	Е	Platform	0	MUXSEL2	MUXSEL1	MUXSEL0	0	SERIRQEN	SPILB	0			
C8F	F	n/a	0	0	0	0	0	0	0	0			
C90	10	POR	0	0	0	0	0	0	AUX_PSEN	MINI_PSDIS			
C91	11	POR	0	W_DISABLE	ETH1_OFF	ETH0_OFF	0	0	0	0			
C92	12	Platform	0	0	0	0	0	PBRESET	0	0			
C93	13	n/a	0	0	0	0	0	0	0	0			
C94	14	n/a	0	0	0	0	0	0	0	0			
C95	15	n/a	0	0	0	0	0	0	0	0			
C96	16	n/a	0	0	0	0	0	0	0	0			
C97	17	n/a	0	0	0	0	0	0	0	0			
C98	18	n/a	0	0	0	0	0	0	0	0			
C99	19	n/a	0	0	0	0	0	0	0	0			
C9A	1A	n/a	0	0	0	0	0	0	0	0			
С9В	1B	n/a	0	0	0	0	0	0	0	0			
C9C	1C	n/a	0	0	0	0	0	0	0	0			
C9D	1D	n/a	0	0	0	0	0	0	0	0			
C9E	1E	n/a	0	0	0	0	0	0	0	0			
C9F	1F	n/a	0	0	0	0	0	0	0	0			
CA0	20	n/a	0	0	0	0	0	0	0	0			
CA1	21	resetSX	DIR_GPIO8	DIR_GPIO7	DIR_GPIO6	DIR_GPIO5	DIR_GPIO4	DIR_GPIO3	DIR_GPIO2	DIR_GPIO1			
CA2	22	resetSX	POL_GPIO8	POL_GPIO7	POL_GPIO6	POL_GPIO5	POL_GPIO4	POL_GPIO3	POL_GPIO2	POL_GPIO1			
CA3	23	resetSX	OUT_GPIO8	OUT_GPIO7	OUT_GPIO6	OUT_GPIO5	OUT_GPIO4	OUT_GPIO3	OUT_GPIO2	OUT_GPIO1			
CA4	24	n/a	IN_GPIO8	IN_GPIO7	IN_GPIO6	IN_GPIO5	IN_GPIO4	IN_GPIO3	IN_GPIO2	IN_GPIO1			
CA5	25	Platform	IMASK_GPIO8	IMASK_GPIO7	IMASK_GPIO6	IMASK_GPIO5	IMASK_GPIO4	IMASK_GPIO3	IMASK_GPIO2	IMASK_GPIO1			
CA6	26	Platform	ISTAT_GPIO8	ISTAT_GPIO7	ISTAT_GPIO6	ISTAT_GPIO5	ISTAT_GPIO4	ISTAT_GPIO3	ISTAT_GPIO2	ISTAT_GPIO1			

SPIDATA2

SPIDATA3 Most Significant Byte and Start SPI Cycle when written

SPIMISC - Custom SPI I/F controls, mSATA/PCIe Mux Select

Reserved

MISCSR1 - Power Control Regs

MISCSR2 - USB, Ethernet Control, misc.

MISCSR3 - Misc Control Reg

Reserved to align 16-bit regs on even byte boundaries

Reserved for Digital I/O registers used on other products

Reserved for Digital I/O registers used on other products

Reserved for Digital I/O registers used on other products

Reserved for Digital I/O registers used on other products

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Reserved for Digital I/O registers used on other products

AUXDIR - AUX GPIO I/O Direction Control

AUXPOL - AUX GPIO I/O Polarity Control

AUXOUT - AUX GPIO I/O Output Value

AUXIN - AUX GPIO I/O Input Value

AUXIMASK- AUX GPIO I/O Interrupt Mask and Control

AUXISTAT - AUX GPIO I/O Interrupt Mask and Status

CA7	27	resetSX	MODE_GPIO8	MODE_GPIO7	MODE_GPIO6	MODE_GPIO5	MODE_GPIO4	MODE_GPIO3	MODE_GPIO2	MODE_GPIO1	AUXMODE1 - AUX GPIO I/O Mode Register		
CA8	28	Platform	IRQEN	IRQSEL2	IRQSEL1	IRQSEL0	0	RESET_EN	WDT_EN	WDT_STAT	WDT_CTL - Watchdog Control		
CA9	29	Platform	msb			<=====	=====>		Isb	WDT_VAL - Watchdog Value (in seconds)			
CAA	2A	Platform	0	0	0	0	0	0	COM2_MODE	COM1_MODE	XCVRMODE - COM Port Transceiver Mode Register (all ports)		
САВ	2B	Platform	IRQEN	IRQSEL2	IRQSEL1	IRQSEL0	0	0	0	0	AUXMODE2		
CAC	2C	Platform	0	0	0	0	0	0	0	FAN_OFF	FANCON - Fan Control		
CAD	2D	n/a	0	0	0	0	0	0	0	0	Reserved for future fan control		
CAE	2E	Platform	msb			<====	=====>			Isb	FANTACHLS - Fan TACH LS 8 Bits		
CAF	2F	Platform	msb			<====	=====>			Isb	FANTACHMS - Fan TACH MS 8 Bits		
СВ0	30	Platform	IRQEN	IRQSEL2	IRQSEL1	IRQSEL0	IMASK_BATTLOW	IMASK_EVENT	IMASK_THERM	IMASK_ALERT	TEMPICR - Temperature (HW Monitor) Interrupt Mask and Control		
CB1	31	Platform	BATTLOW	0	0	0	ISTAT_BATTLOW	ISTAT_EVENT	ISTAT_THERM	ISTAT_ALERT	TEMPISTAT - Temperature Interrupt Mask and Status		
CB2	32	Platform	IRQEN	IRQSEL2	IRQSEL1	IRQSEL0	UART1_BASE3	UART1_BASE2	UART1_BASE1	UART1_BASE0	UART1CR - Internal UART1 Control Register		
СВЗ	33	Platform	IRQEN	IRQSEL2	IRQSEL1	IRQSEL0	UART2_BASE3	UART2_BASE2	UART2_BASE1	UART2_BASE0	UART2CR - Internal UART2 Control Register		
CB4	34	n/a	0	0	0	0	0	0	0	0	Reserved for UART3CR		
CB5	35	n/a	0	0	0	0	0	0	0	0	Reserved for UART4CR		
СВ6	36	Platform	0	0	UART2_485ADC	UART1_485ADC	0	0	UART2_EN	UART1_EN	UARTMODE1 - UART Mode register #1		
СВ7	37	Platform	0	0	0	0	0	0	0	FAST_MODE	UARTMODE2 - UART Mode register #2		
СВ8	38	n/a	0	0	0	0	0	0	0	0	Reserved		
СВ9	39	n/a	0	0	0	0	0	0	0	0	Reserved		
СВА	3A	n/a	0	0	0	0	0	0	0	0	Reserved		
СВВ	3B	n/a	0	0	0	0	0	0	0	0	Reserved		
СВС	3C	Platform	msb	<>							8254 Timers Address 0		
CBD	3D	Platform	msb	<=====>							8254 Timers Address 1		
CBE	3E	Platform	msb			<====	=====>		Isb	8254 Timers Address 2			
CBF	3F	Platform	msb			<====	=====>		Isb	8254 Timers Address 3			

# **FPGA Register Descriptions**

	Register Access Key								
R/W Read/Write									
RO	Read-only (status or reserved)								
R/WC	Read-status/Write-1-to-Clear								
RSVD	Reserved. Only write 0 to this bit; ignore all read values.								

# **Product Information Registers**

This register drives the PLED on the paddleboard. It also provides read access to the product code.

Table 4: PCR – Product Code and LED Register

Bit	Identifier	Access	Default	Description
				Drives the programmable LED on the paddleboard.
7	PLED R/W 0		0	0 – LED is off (default)
				1 – LED is on (can be used by software)
6-0	PRODUCT_CODE	RO	0010101	Product Code for the EPMe-42 (0x15)

Table 5: PSR - Product Status Register

Bit	Identifier	Access	Default	Description
7:3	REV_LEVEL[4:0]	RO	N/A	Revision level of the PLD (incremented every FPGA release)
2	EXTEMP	RO	N/A	Extended or Standard Temp Status (set via external resistor):  0 – Standard Temp  1 – Extended Temp (probably always set)
1	CUSTOM	RO	N/A	Custom or Standard Product Status  0 – Standard Product  1 – Custom Product or PLD/FPGA
0	ВЕТА	RO	N/A	Beta or Production Status 1 – Beta (or Debug) 0 – Production

## **BIOS and Jumper Status Register**

Table 6: SCR -Status/Control Register

Bit	Identifier	Access	Default	Description
				Status of the external BIOS switch (jumper):
7	BIOS_JMP	RO	N/A	1 – Primary BIOS selected
				0 – Secondary BIOS selected
				BIOS Switch (jumper) Override
6	BIOS OR	R/W	0	0 – BIOS Select will follow the BIOS_JMP switch setting. (Note)
O	BIOG_OK	17/ 77	U	1 – BIOS Select will follow the BIOS_SEL register setting
				Note: See Table 7
				BIOS Select (see BIOS_OR):
5	BIOS SEL	R/W	0	1 – Primary BIOS selected
Э	BIOS_SEE	10,00		0 – Backup BIOS selected
				Note: See Table 7
			0	Debug LED (controls the yellow LED):
4	LED_DEBUG	R/W		0 – LED is off and follows its primary function (MSATA_DAS)
				1 – LED is on (indicates FPGA is programmed by default)
				Status used to indicate that the FPGA is not officially released
3	WORKVER	RO	N/A	and is still in a working state.
· ·				0 – FPGA is released
				1 – FPGA is in a working state (not released)
2	RESERVED	RO	N/A	Reserved. Writes are ignored; reads always return 0.
				Status of the GPI Jumper (switch):
1	GPI_JMP	RO	N/A	0 – Switch is Off
				1 – Switch is On
0	RESERVED	RO	0	Reserved. Writes are ignored; reads always return 0.

**Note:** This corresponds to the setting of position 6 of the SW1 Configuration Switch block. Refer to the *EPMe-42 Hardware Reference Manual* for more information regarding the configuration switches.

The table below summarizes the modes related to BIOS\_OR and BIOS\_SEL and the BIOS Configuration Switch 6. The external BIOS selection is determined by the combination of the FPGA BIOS selection signals and the BIOS Configuration Switch. This allows the BIOS Configuration switch to still be used to select the Secondary BIOS no matter what the internal FPGA settings are or when the FPGA is not programmed (i.e., setting the BIOS Configuration to the "ON" position will always select the Secondary).

Table 7: BIOS Selection

BIOS_OR (Bit 6)	BIOS_SEL (Bit 5)	BIOS Configuration Switch #6 Position	BIOS Selected	Comments
'0'	'X' (don't care)	"OFF"	Primary	Configuration Switch selects the BIOS (BIOS_SEL ignored)
'0'	'X' (don't care)	"ON"	Secondary	Configuration Switch selects the BIOS (BIOS_SEL ignored)
<b>'1'</b>	<b>'1'</b>	"OFF"	Primary	BIOS_SEL selects BIOS
<b>'1'</b>	<b>'1'</b>	"ON"	Secondary	Configuration Switch selects BIOS
<b>'1'</b>	'0'	"OFF"	Secondary	BIOS_SEL selects BIOS
<b>'1'</b>	'0'	"ON"	Secondary	Configuration Switch selects BIOS

# **Timer Registers**

The FPGA implements an 8254-compatible timer/counter that includes three 16-bit timers.

Table 8: TICR - 8254 Timer Interrupt Control Register

Bit	Identifier	Access	Default	Description
				8254 Timer interrupt enable/disable:
7	IRQEN	R/W	0	0 – Interrupts disabled
				1 – Interrupts enabled
				8254 Timer interrupt IRQ select in LPC SERIRQ:
				000 – IRQ3
				001 – IRQ4
				010 – IRQ5
6-4	IRQSEL(2:0)	R/W	000	011 – IRQ10
				100 – IRQ6
				101 – IRQ7
				110 – IRQ9
				111 – IRQ11
3	RESERVED	RO	0	Reserved. Writes are ignored; reads always return 0.
				8254 timer #5 interrupt mask:
2	IMSK_TC5	R/W	0	0 - Interrupt disabled
				1 – Interrupt enabled
				8254 timer #4 interrupt mask:
1	IMSK_TC4	R/W	0	0 - Interrupt disabled
				1 – Interrupt enabled
				8254 timer #3 interrupt mask:
0	IMSK_TC3	R/W	0	0 – Interrupt disabled
				1 – Interrupt enabled

Table 9: TISR – 8254 Timer Interrupt Status Register

Bit	Identifier	Access	Default	Description
7	INTRTEST	R/W	0	Debug/Test Only 8254 Timer Interrupt Test (test mode only): 0 - No test interrupt 1 - If IRQEN is a 1 then an interrupt will assert in the selected IRQ in the LPC SERIRQ stream (no timer interrupt mask needs to be set for this)
	TMRTEST	R/W	0	Debug/Test Only 8254 Timer Test Mode:
				0 – Normal operation
6				1 – Timer test mode. In the mode the OCTC3, OCTC4 (and OCTC5 is ever implemented) outputs are set to Hi-Z and the ICTC3, ICTC4 timer inputs are ignored.
5	TMRIN4	R/W	0	Debug/Test Only 8254 Timer #4 test signal. When INTRTEST = 1 this signal is used for the timer input control instead of the external ICTC4 signal. When INTRTEST = 0 this is ignored.
				0 – deasserted
				1 – asserted
4	TMRIN3	R/W	0	Debug/Test Only 8254 Timer #3 test signal. When INTRTEST = 1 this signal is used for the timer input control instead of the external ICTC3 signal. When INTRTEST = 0 this is ignored.
				0 – deasserted
				1 – asserted
3	RESERVED	RO	0	Reserved. Writes are ignored; reads always return 0.
				Status for the 8254 Timer #5 output (terminal count) interrupt when read. This bit is read-status and a write-1-to-clear.
2	ISTAT_TC5	RW/C	N/A	0 – Timer output (terminal count) has not transitioned from 0 to a 1 level
				1 – Timer output (terminal count) has transitioned from a 0 to a 1 level
				Status for the 8254 Timer #4 output (terminal count) interrupt when read. This bit is read-status and a write-1-to-clear.
1	ISTAT_TC4	RW/C	N/A	0 – Timer output (terminal count) has not transitioned from 0 to a 1 level
				1 – Timer output (terminal count) has transitioned from a 0 to a 1 level
				Status for the 8254 Timer #3 output (terminal count) interrupt when read. This bit is read-status and a write-1-to-clear.
0	ISTAT_TC3	RW/C	N/A	0 – Timer output (terminal count) has not transitioned from 0 to a 1 level
				1 – Timer output (terminal count) has transitioned from a 0 to a 1 level

Table 10: TCR - 8254 Timer Control Register

Bit	Identifier	Access	Default	Description
				Controls the "gate" signal on 8254 timer #5 when not using an external gate signal:
7	TMR5GATE	R/W	0	0 – Gate on signal GCTC5 is disabled 1 – Gate on signal GCTC5 is enabled
				Always set to 0 when configuring timer modes. Set to a '1' if using external clocking. It can be turned on and off when using internal clocking.
				Controls the "gate" signal on 8254 timer #4 when not using an external gate signal:
6	TMR4GATE	R/W	0	0 – Gate on signal GCTC4 is disabled 1 – Gate on signal GCTC4 is enabled
				Always set to 0 when configuring timer modes. Set to a '1' if using external clocking. It can be turned on and off when using internal clocking.
				Controls the "gate" signal on 8254 timer #3 when not using an external gate signal:
5	TMR3GATE	R/W	0	0 – Gate on signal GCTC3 is disabled 1 – Gate on signal GCTC3 is enabled
				Always set to 0 when configuring timer modes. Set to a '1' if using external clocking. It can be turned on and off when using internal clocking.
				Mode to set timers #4 and #5 in:
4	TM45MODE	E R/W	8/W 0	0 – Timer #4 and #5 form one 32-bit timer controlled by timer #1 signals 1 – Timer #4 and Timer #5 are separate 16-bit timers with their own control signals.
				Almost always used in 32-bit mode especially when TMRFULL is a '0' (the 16-bit timer #5 if of limited use)
				Timer #4 Clock Select:
3	TM4CLKSEL	R/W	0	0 – Use internal 4.125 MHz clock (derived from PCI clock) 1 – Use external ICTC4
				Timer #5 is always on internal clock if configured as a 16-bit clock
				Timer #3 Clock Select:
2	TM3CLKSEL	R/W	0	0 – Use internal 4.125 MHz clock (derived from PCI clock) 1 – Use external ICTC3 assigned to Digital I/O
				Debug/Test Only: Used to derive OCTCx outputs with TIMxGATE signals for continuity testing only:
1	TMROCTST	R/W	0	0 – Normal operation
				1 – Drive OCTCx outputs with corresponding TMRxGATE control registers (e.g., OCTC4 with TMR4GATE) for continuity testing.
0	Reserved	R/W	0	Reserved. Writes are ignored; reads always return 0.

# **SPI Control Registers**

These are placed at the traditional offset 0x8 location. Only external SPX interface devices use this interface. Because the board uses a 9-pin SPX connector, only two devices are supported.

#### **SPICONTROL**

**Table 11: SPI Interface Control Register** 

Bit	Identifier	Access	Default	Description
7	CPOL	R/W	SPI clock polarity – Sets the SCLK idle state.  0 – SCLK idles low 1 – SCLK idles high	
6	СРНА	R/W	0	SPI clock phase – Sets the SCLK edge on which valid data will be read.  0 – Data is read on rising edge  1 – Data is read on falling edge
5-4	SPILEN(1:0)	R/W	Determines the SPI frame length. This selection works in manual auto slave select modes.  00 00 - 8-bit 01 - 16-bit 10 - 24-bit 11 - 32-bit	
3	MAN_SS	R/W	0	Determines whether the slave select lines are asserted through the user software or are automatically asserted by a write to SPIDATA3.  0 - The slave select operates automatically  1 - The slave select line is controlled manually through SPICONTROL bits SS[2:0]
2-0	SS(2:0)	R/W	000	SPI slave device selection:  000 – None 001 – SS0# 010 – SS1# 011 – Undefined (ignored) 100 – Undefined (ignored) 101 – Undefined (ignored) 101 – Undefined (ignored) 110 – Undefined (ignored) 111 – Undefined (ignored)

#### **SPISTATUS**

The SPX interrupt is not connected on this product. The control bits and status associated are still defined in the register set but the SPX interrupt will always be de-asserted.

**Table 12: SPI Interface Status Register** 

Bits	Identifier	Access	Default	Description
				Select which IRQ will be enabled if HW_IRQ_EN = 1, interrupts are not used on this board so this just becomes a read/write non-functional field.
				00 – IRQ3
7-6	IRQSEL[1:0]	R/W	00	01 – IRQ4
				10 – IRQ5
				11 – IRQ10
				Note: These are the first 4 interrupts in the "usual" LPC SERIRQ group of 8 interrupts.
				Select one of four SCLK frequencies. This is based on a 24Mhz LPC clock.
F 4	CDICLICIA.01	DAM	00	00 – 0.75 Mhz (24Mhz /32)
5-4	SPICLK[1:0]	R/W	00	01 – 1.5 Mhz (24Mhz /16)
				10 – 3 Mhz (24Mhz /8)
				11 – 6 Mhz (24Mhz /4)
3	HW_IRQ_EN	R/W	0	This enables the selected IRQ to be activated by a SPI device that is configured to use interrupt capability. SPX I/F interrupts are not supported on this product.
_				0 - IRQ's are disabled for SPI operations.
				1 - the IRQ can be asserted
				Controls the SPI shift direction from the SPIDATA(x) registers.
2	LSBIT_1ST	R/W	0	0 - Data is left-shifted (MSB first).
				1 - Data is right-shifted (LSB first)
				Status flag which indicates when the hardware SPX signal SINT# is asserted. SPX I/F interrupts are not supported on this product so this always returns a 0
1	HW_INT	RO	0	0 - the hardware interrupt SINT# is de-asserted.
'	1100_1101	I(O	O	1 - an interrupt is present on SINT#
				If HW_IRQ_EN= 1, then the selected IRQ will also be asserted by the hardware interrupt. HW_INT is read-only and is cleared when the external hardware interrupt is no longer present.
				Status flag which indicates when an SPI transaction is underway. I <sup>2</sup> C is so slow that there is no reason to ever poll this.
0	BUSY	RO	N/A	0 - The SPI bus is idle.
				1 - SCLK is clocking data in/out of the SPIDATA(x) registers (that is, busy)

## **SPI Data Registers**

There are four data registers used on the SPI interface. How many are used depends on the device being communicated with. SPIDATA0 is typically the least significant byte and SPIDATA3 is the most significant byte. Any write to the most significant byte SPIDATA3 initiates the SCLK and, depending on the MAN\_SS state, will assert a slave select to begin an SPI bus transaction.

Data is sent according to the LSBIT\_1ST setting. When LSBIT\_1ST = 0, the MSbit of SPIDATA3 is sent first and received data will be shifted in the LSbit of the selected frame size determined by SPILEN1 and SPILEN0. When LSBIT\_1ST = 1, the LSbit of the selected frame size is sent first and the received data will be shifted in the MSbit of SPIDATA3.

#### **SPIDATA0** (Least Significant Byte)

D7	D6	D5	D4	D3	D2	D1	D0
MSB							LSB

#### SPIDATA1

D7	D6	D5	D4	D3	D2	D1	D0
MSB							LSB

#### SPIDATA2

D7	D6	D5	D4	D3	D2	D1	D0
MSB							LSB

#### SPIDATA3 (Most Significant Byte) [Cycle Trigger Register]

D7	D6	D5	D4	D3	D2	D1	D0
MSB							LSB

# SPI Debug Control Register and mSATA/PCIe Select Control Register

This register is only used to set an SPI loopback (debug/test only) but is also used for the mSATA/PCIe Minicard Mux select.

Table 13: SPI – SPI Debug Control Register

Bit	Identifier	Access	Default	Description			
7	Reserved	RO	0	Reserved. Writes are ignored; reads always return 0.			
6-4	MUXSEL(2:0)	R/W	000	<ul> <li>mSATA/PCIe Mux selection for Minicard slot (and 2<sup>nd</sup> SATA connector):</li> <li>000 – Select mSATA using only pin 43 (MSATA_DETECT). This is an Intel-mode that is reliable for PCIe Minicards but not for mSATA modules that inadvertently ground this signal.</li> <li>001 – Use only Pin 51 (PRES_DISABLE2#). This is the default method and is defined in the Draft mSATA spec but some Minicards use it as a second wireless disable.</li> <li>010 – Use either Pin 43 or Pin 51. This will work just like 001 because Pin 43 is disabled by an FPGA pull-down.</li> <li>011 – Force PCIe mode on the Minicard</li> <li>100 – Force mSATA mode on the Minicard.</li> <li>101 – Undefined (same as 000)</li> <li>110 – Undefined (same as 000)</li> <li>Note: When the Minicard uses PCIe, the SATA channel automatically switches to the SATA connector.</li> </ul>			
3	Reserved	RO	0	Reserved. Writes are ignored; reads always return 0.			
2	SERIRQEN	R/W	0	When an IRQ is assigned a slot in the SERIRQ, it will drive the slot with the interrupt state, but this bit must be set to a '1' to do that.  0 – Slots assigned to SERIRQ are not driven (available for other devices).  1 – Slots assigned to SERIRQ are driven with their current interrupt state (which is low since interrupts are high-true).  This is because the default interrupt settings in this FPGA can conflict with other interrupts if the VersaAPI is not being used (for example, console redirect using IRQ3).			
1	SPILB	R/W	0	Debug/Test Only: Used to loop SPI output data back to the input (debug/test mode).  0 - Normal operation  1 - Loop SPI output data back to the SPI input data (data output still active)			
0	RESERVED	RO	0	Reserved. Writes are ignored; reads always return 0.			

# **Miscellaneous FPGA Registers**

#### MISCR1 - Miscellaneous Control Register #1

This is a register in the always-on power well of the FPGA. It holds its state during sleep modes and can only be reset by a power cycle. This is a placeholder register for features like pushing the power-button and also for software initiated resets should those be needed. This register is only reset by the main power-on reset since it must maintain its state in Sleep modes (for example, S3).

Table 14: MISCR1 - Misc. Control Register #1

Bits	Identifier	Access	Default	Description
7-2	Reserved	RO	000000	Reserved. Writes are ignored; reads always return 0.
1	AUX_PSEN	R/W	0	AUX GPIO Bank I/O Power Enable  0 – The AUX GPIO bank will be powered down in sleep modes (only power in S0)  1 – The AUX GPIO bank will not be powered down in sleep modes and the configuration will remain.  The GPIO bank power switch is controlled by the "OR" of the S0 power control signal and FPGA_PSEN.  Note: Some register resets are conditional on the state of AUX_PSEN
0	MINI_PSDIS	R/W	0	Minicard 3.3 V power disable  0 – Minicard 3.3 V power stays on always (this is normally how minicards operate if they support any Wake events)  1 – Minicard 3.3 V power will be turned off when not in S0 (in sleep modes).  The Minicard 3.3 V power switch is controlled by the "OR" of the S0 power control signal and the inverse of MINI_PSDIS.

#### MISCR2 - Miscellaneous Control Register #2

This is a register in the always-on power well of the FPGA. It holds its state during sleep modes and can only be reset by a power cycle. It is primarily used for control signals for the always-powered Ethernet controllers and the USB hubs. This register is only reset by the main power-on reset since it must maintain its state in sleep modes (for example, S3).

Table 15: MISCSR2 – Misc. Control Register #2

Bit	Identifier	Access	Default	Description
7	RESERVED	RO	0's	Reserved – Writes are ignored. Reads always return 0
				Used to control the W_DISABLE (Wireless Disable) signal going to the PCle Mincard:
6	W_DISABLE	R/W	0	0 – W_DISABLE signal is not asserted (Enabled) 1 – W_DISABLE signal is asserted (Disabled)
				<b>Note:</b> There are other control sources that can be configured to control this signal and if enabled the control becomes the "OR" of all sources
5	ETHOEE1	R/W	0	Used to disable the Ethernet controller #1 (controls the ETH_OFF# input to the I210-IT):
5	ETHOFF1 R/W	U	0 – Ethernet controller is enabled (On) 1 – Ethernet controller is disabled (Off)	
4	FTHOFF0	R/W	0	Used to disable the Ethernet controller #0 (controls the ETH_OFF# input to the I219 Ethernet PHY):
4	ETHOFFU	10,00	U	0 – Ethernet Phy controller is enabled (On) 1 – Ethernet Phy controller is disabled (Off)
3	RESERVED	RO	0's	Reserved – Writes are ignored. Reads always return 0
2	RESERVED	RO	0's	Reserved – Writes are ignored. Reads always return 0
1	RESERVED	RO	0's	Reserved – Writes are ignored. Reads always return 0
0	RESERVED	RO	0's	Reserved – Writes are ignored. Reads always return 0

## MISCR3 - Miscellaneous Control Register #3

This register sets the SMBus addresses on the 4-Port PCIe Switch.

Table 16: MISCR3 - Misc. Control Register #3

Bits	Identifier	Access	Default	Description
7-4	Reserved	RO	0	Reserved. Writes are ignored; reads always return 0.
3	Reserved	RO	0	Reserved. Writes are ignored; reads always return 0.
2	PBRESET	R/W		When written to, this will do the same thing as pushing the reset button, which could be useful for a software-initiated watchdog.  0 – No action  1 – Activate the reset push-button  Note: Because this generates a reset that will reset this register, it isn't likely a value of a '1' can ever be read-back, so it is somewhat
				"write-only".
1-0	Reserved	RO	0	Reserved. Writes are ignored; reads always return 0.

#### **AUXDIR – AUX GPIO Direction Control Register**

This register controls the direction of the eight AUX GPIO signals.

This reset depends on the state of the FPGA\_PSEN signal. If FPGA\_PSEN is a '0' then the reset is the power-on and Platform Reset. If FPGA\_PSEN is a '1' then this register is only reset at power-on.

Table 17: AUXDIR - AUX GPIO Direction Control Register

Bit	Identifier	Access	Default	Description
7-0	DIR_GPIO[8:1]	R/W	0	Sets the direction of the AUX GPIOx lines. For each bit:  0 – Input  1 – Output

#### AUXPOL – AUX GPIO Polarity Control Register

This register controls the polarity of the eight AUX GPIO signals.

This reset depends on the state of the FPGA\_PSEN signal. If FPGA\_PSEN is a '0' then the reset is the power-on and Platform Reset. If FPGA\_PSEN is a '1' then this register is only reset at power-on.

Table 18: AUXPOL - AUX GPIO Polarity Control Register

Bits	Identifier	Access	Default	Description
7-0	POL_GPIO[8:1]	R/W	0	Sets the polarity of the AUX GPIOx lines. For each bit:  0 – No inversion  1 – Invert  Note: This impacts the polarity as well as the interrupt status edge used.

#### **AUXOUT - AUX GPIO Output Control Register**

This register sets the AUX GPIO output value. This value will only set the actual output if the GPIO direction is set as an output. Reading this register does not return the actual input value of the GPIO (use the AUXIN register for that). As such, this register can actually be used to detect input/output conflicts.

This reset depends on the state of the FPGA\_PSEN signal. If FPGA\_PSEN is a '0' then the reset is the power-on and Platform Reset. If FPGA\_PSEN is a '1' then this register is only reset at power-on.

Table 19: AUXOUT - AUX GPIO Output Control Register

Bits	Identifier	Access	Default	Description
7-0	OUT_GPIO[8:1]	R/W	0	Sets the AUX GPIOx output values. For each bit:  0 – De-asserts the output (0 if polarity not-inverted, 1 if inverted)  1 – Asserts the output (1 if polarity not-inverted, 0 if inverted)

#### AUXIN - AUX GPIO I/O Input Status Register

This registers sets the AUX GPIO input value. It will read the input value regardless of the setting on the direction (that is, it always reads the input). This reads the actual state of the GPIO pin into the part.

Table 20: AUXIN - AUX GPIO Input Status Register

Bits	Identifier	Access	Default	Description
7-0	IN_GPIOIO[8:1]	RO	N/A	Reads the GPIOx input status. For each bit:  0 – Input de-asserted if polarity not-inverted; asserted if polarity inverted  1 Input asserted if polarity not-inverted; de-asserted if polarity inverted

#### AUXIMASK - AUX GPIO Interrupt Mask Register

This is the interrupt mask registers for the AUX GPIOs and the interrupt enable selection. The reset type is Platform Reset because interrupts always have to be setup after exiting sleep states.

Table 21: AUXICR - AUX GPIO Interrupt Mask Register

Bits	Identifier	Access	Default	Description
7-0	IMASK_GPIO[8:1]	R/W	0	GPIOx interrupt mask. For each bit:  0 – Interrupt disabled  1 – Interrupt enabled

#### AUXISTAT - AUX GPIO I/O Interrupt Status Register

Table 22: AUXISTAT - AUX GPIO Interrupt Status Register

Bits	Identifier	Access	Default	Description
7-0	ISTAT_GPIO[8:1]	RW/C	N/A	GPIOx interrupt status. A read returns the interrupt status. Writing a '1' clears the interrupt status.  This bit is set to a '1' on a transition from low-to-high (POL_DIOx=0) or high-to-low (POL_DIOx=1).

#### AUXMODE1- AUX I/O Mode Register #1

These two registers selected the mode on each AUX GPIO. This reset depends on the state of the FPGA\_PSEN signal. If FPGA\_PSEN is a '0' then the reset is the power-on and Platform Reset. If FPGA\_PSEN is a '1' then this register is only reset at power-on.

Table 23: AUXMODE1 – AUX I/O Mode Register

Bit	Identifier	Access	Default	Description
				GPIO 8 Mode:
7	MODE_GPIO8	R/W	0	0 – GPIO (I/O)
				1 – ICTC3 (input)
				GPIO 7 Mode:
6	MODE_GPIO7	R/W	0	0 – GPIO (I/O)
				1 – ICTC4 (input)
				GPIO 6 Mode:
5	MODE_GPIO6	R/W	0	0 – GPIO (I/O)
				1 – OCTC3 (output)
				GPIO 5 Mode:
4	MODE_GPIO5	R/W	0	0 – GPIO (I/O)
				1 – OCTC4 (output)
				GPIO 4 Mode:
3	MODE_GPIO4	R/W	0	0 – GPIO (I/O)
				1 – WDOG_RESET# (Output)
				GPIO 3 Mode:
2	MODE_GPIO3	R/W	0	0 – GPIO (I/O)
				1 – WAKE# (Input)
				GPIO 2 Mode:
1	MODE_GPIO2	R/W	0	0 – GPIO (I/O)
				1 – W_DISABLE# (Input)
				GPIO 1 Mode:
0	MODE_GPIO1	R/W	0	0 – GPIO (I/O)
				1 – PWM (output)

## WDT\_CTL - Watchdog Control Register

Reset type is Platform.

Table 24: WDT\_CTL – Watchdog Control Register

Bits	Identifier	Access	Default	Description
				Watchdog interrupt enable/disable:
7	IRQEN	R/W	0	0 – Interrupts disabled
				1 – Interrupts enabled
				Watchdog interrupt IRQ select in LPC SERIRQ:
				000 – IRQ3
				001 – IRQ4
				010 – IRQ5
6-4	IRQSEL(2:0)	R/W	000	011 – IRQ10
				100 – IRQ6
				101 – IRQ7
				110 – IRQ9
				111 – IRQ11
3	Reserved	RO	0	Reserved. Writes are ignored; reads always return 0.
				Enable the Watchdog to assert the push-button reset if it "fires".
2	RESET_EN	R/W	0	0 – Watchdog will not reset the board
				1 – Board will be reset if the Watchdog "fires"
				Watchdog Enable:
1	WDT EN	R/W	0	0 – Watchdog is disabled
'	WDI_LIN	1000	0	1 – Watchdog is enabled
				Note: The WDT_VAL register must be set before enabling.
				Watchdog Status:
				0 – Watchdog disabled or watchdog has not "fired"
				1 – Watchdog fired.
0	WDT_STAT	RO	0	<b>Note:</b> Once set to a '1', it will remain so until any of the following occurs:
				the WDT_VAL register is written to
				the WDT_EN is disabled
				a reset occurs

#### WDT\_VAL - Watchdog Value Register

This register sets the number of seconds for a Watchdog prior to enabling the watchdog. By writing this value, the watchdog can be prevented from "firing". A watchdog fires whenever this registers value is all 0s, so it must be set to a non-zero value before enabling the watchdog to prevent an immediate "firing". Reset type is Platform.

The value written should always be 1 greater than the desired timeout value due to a 0-1 second "tick" error band (values written should range from 2-255 because a 1 could cause an immediate trigger); that is, the actual timeout is WDT\_VAL seconds with a -1 second to 0 second error band.

Table 25: WDT\_VAL - Watchdog Control Register

Bits	Identifier	Access	Default	Description
7-0	WDT_VAL(7:0)	R/W	0x00	Number of seconds before the Watchdog fires. By default, it is set to zero which results in an immediate watchdog if WDT_EN is set to a '1'.

#### XCVRMODE - COM Transceiver Mode Register

Sets the RS232 vs RS422/485 mode on the COM port Transceivers. These drive the UART\_SEL signals from the FPGA to the Transceivers.

Reset type is Platform.

**Note:** The values shown are for the default BIOS configuration.

Table 26: XCVRMODE - COM Transceiver Mode Register

Bits	Identifier	Access	Default	Description
7-4	Reserved	RO	0000	Reserved. Writes are ignored; reads always return 0.
3-2	Reserved	RO	00	Reserved. Writes are ignored; reads always return 0.
1	COM2_MODE	R/W	0	COM2 Transceiver mode: 0 – RS232 1 – RS422/485
0	COM1_MODE	R/W	0	COM1 Transceiver mode: 0 – RS232 1 – RS422/485

#### AUXMODE2- AUX I/O Mode Register #2

This register defines the interrupt mapping for the AUX GPIOs. Reset type is Platform.

Table 27: AUXMODE2 - AUX I/O Mode Register #2

Bits	Identifier	Access	Default	Description
'				AUX GPIO interrupt enable/disable:
7	IRQEN	R/W	0	0 – Interrupts disabled
				1 – Interrupts enabled
				AUX GPIO interrupt IRQ select in LPC SERIRQ:
				000 – IRQ3
				001 – IRQ4
				010 – IRQ5
6-4	IRQSEL(2:0)	R/W	000	011 – IRQ10
				100 – IRQ6
				101 – IRQ7
				110 – IRQ9
				111 – IRQ11
3-0	Reserved	RO	0000	Reserved. Writes are ignored; reads always return 0.

#### FANCON - Fan Control Register

The fan is always off in any sleep mode. When the processor comes out of a sleep state, this register must be setup again since it will be reset to default by the platform reset signal. The fan is always turned "off" in sleep modes. No PWM fan control is supported on the EPMe-42.

Reset type is Platform.

**Note:** The BIOS (via ACPI) may modify this register when in an ACPI-capable operating system. The register can be read for status purposes but do not write to it unless you are using a non-ACPI operating system.

Table 28: FANCON - Fan Control Register

Bits	Identifier	Access	Default	Description
7-1	Reserved	RO	0000000	Reserved. Writes are ignored; reads always return 0.
0	FAN_OFF	R/W	0	Fan enable: 0 – Fan is on 1 – Fan is off

#### FANTACHLS, FANTACHMS – Fan Tach Status Registers

These registers contain the number of fan tach output samples over a one-second sampling period. The value is always valid after the fan speed stabilizes and is updated every 1 second (after a delay of 1 second). Currently, only the lower 10-bits have a valid tach reading (that is, the upper 6 bits will always be zero). The fan tach count should never overflow in the one second period, but it if does, the value will "stick" at 0x03FF.

The board can handle up at least a 10,000 RPM fan with a fan tach output of up to four uniform pulses per revolution. The duty cycle of the fan tach output pulse can be as low as 25% (typically they are very close to 50%). The conversion to RPM is as follows:

 $RPM = (FANTACH \times 60) / PPR$ 

#### Where...

- FANTACH the 16-bit register reading
- PPR fan tach pulses per revolution (typically either 1, 2, or 4)

Reset type is n/a.

Table 29: FANTACHLS - FANTACH Status Register Least Significant Bits

Bits	Identifier	Access	Default	Description
7-0	FANTACH[7:0]	RO	N/A	Least significant eight bits of FANTACH.  Read this register first since it latches the value for the most significant eight bits.

Table 30: FANTACHMS - FANTACH Status Register Most Significant Bits

Bits	Identifier	Access	Default	Description
7-0	7-0 FANTACH[15:8]	RO	N/A	Most significant eight bits of FANTACH.
	TANTAOH[13.0]	11.0		Read this register after reading FANTACHLS.

#### Integrator's Note:

The FANTACHLS register must be read first. It will latch a copy of the MS bits so that when FANTACHMS is read, it is based on the same 16-bit value. This assumes that a 16-bit word read on the LPC bus reads the even (LS) address before the odd (MS) address.

#### **TEMPICR – Temperature Interrupt Control Register**

This is the interrupt mask register for the temperature sensor thermal alerts and the DDR3 SODIMM EVENT signals and the interrupt enable and selection. The SODIMM may not have any temperature event capability.

Reset type is Platform.

Table 31: TEMPICR - Temperature Interrupt Control Register

Bits	Identifier	Access	Default	Description
7	IRQEN	R/W	0	Temperature interrupt enable/disable: 0 – Interrupts disabled 1 – Interrupts enabled
6-4	IRQSEL(2:0)	R/W	000	Temperature interrupt IRQ select in LPC SERIRQ:  000 – IRQ3  001 – IRQ4  010 – IRQ5  011 – IRQ10  100 – IRQ6  101 – IRQ7  110 – IRQ9  111 – IRQ11
3	IMASK_BATTLOW	R/W	0	Battery-low interrupt mask: 0 – Interrupt disabled 1 – Interrupt enabled.
2	IMASK_EVENT	R/W	0	SODIMM EVENT output interrupt mask: 0 – Interrupt disabled 1 – Interrupt enabled.
1	IMASK_THERM	R/W	0	Temperature Sensor THERM output interrupt mask: 0 – Interrupt disabled 1 – Interrupt enabled.
0	IMASK_ALERT	R/W	0	Temperature Sensor ALERT output interrupt mask: 0 – Interrupt disabled 1 – Interrupt enabled.

## **TEMPISTAT – Temperature Interrupt Status Register**

Reset type: n/a.

Table 32: TEMPISTAT – Temperature Interrupt Status Register

Bits	Identifier	Access	Default	Description
7	IN_BATTLOW	RO	N/A	Reads the battery low input status.  0 – battery-low is de-asserted (battery is OK)  1 – battery-low is asserted (battery is low)
6-4	Reserved	RO	000	Reserved. Writes are ignored; reads always return 0.
3	ISTAT_BATTLOW	RW/C	N/A	Battery-Low interrupt status. A read returns the interrupt status. Writing a '1' clears the interrupt status. This bit is set to a '1' on a transition from de-asserted-to-asserted
2	ISTAT_EVENT	RW/C	N/A	SODIMM EVENT interrupt status. A read returns the interrupt status. Writing a '1' will clear the interrupt status
1	ISTAT_THERM	RW/C	N/A	Temperature Sensor THERM interrupt status. A read returns the interrupt status. Writing a '1' clears the interrupt status
0	ISTAT_ALERT	RW/C	N/A	Temperature Sensor ALERT interrupt status. A read returns the interrupt status. Writing a '1' clears the interrupt status

#### **UART1CR – UART1 Control Register (COM1)**

Reset type is Platform.

**Note:** The BIOS (via ACPI) may modify this register when in an ACPI-capable operating system. The register can be read for status purposes but do not write to it unless you are using a non-ACPI operating system.

Table 33: UART1CR - UART1 Control Register (COM1)

Bits	Identifier	Access	Default	Description
				UART interrupt enable/disable:
7	IRQEN	R/W	0	0 – Interrupts disabled
				1 – Interrupts enabled
				UART Interrupt IRQ Select in LPC SERIRQ:
				000 – IRQ3
				001 - IRQ4 <= COM1 Default
				010 – IRQ5
6-4	IRQSEL(2:0)	R/W	001	011 – IRQ10
				100 – IRQ6
				101 – IRQ7
				110 – IRQ9
				111 – IRQ11
				UART Base Address:
	UART1_BASE(3:0)	R/W	0000	0000 - 3F8h <= COM1 Default
				0001 - 2F8h
				0010 - 220h
				0011 - 228h
				0100 - 238h
3-0				0101 - 2E8h
				0110 - 338h
				0111 - 3E8h
				1000 - 200h (requires using LPC generic I/O) Reserved to Customer
				1001 - 208h (requires using LPC generic I/O) Reserved to Customer
				1010-1111 - Reserved, do not use

#### **UART2CR – UART2 Control Register (COM2)**

Reset type is Platform.

**Note:** The BIOS (via ACPI) may modify this register when in an ACPI-capable operating system. The register can be read for status purposes but do not write to it unless you are using a non-ACPI operating system.

Table 34: UART2CR - UART2 Control Register (COM2)

Bits	Identifier	Access	Default	Description
				UART interrupt enable/disable:
7	IRQEN	R/W	0	0 – Interrupts disabled
				1 – Interrupts enabled
				UART interrupt IRQ select in LPC SERIRQ:
				000 − IRQ3 [← COM2 Default]
				001 – IRQ4
				010 – IRQ5
6-4	IRQSEL(2:0)	R/W	000	011 – IRQ10
				100 – IRQ6
				101 – IRQ7
				110 – IRQ9
				111 – IRQ11
				UART Base Address:
	UART2_BASE(3:0)	R/W	0001	0000 - 3F8h
				0001 - 2F8h <= <b>COM2 Default</b>
				0010 - 220h
				0011 - 228h
				0100 - 238h
3-0				0101 - 2E8h
				0110 - 338h
				0111 - 3E8h
				1000 - 200h (requires using LPC generic I/O) Reserved to Customer
				1001 - 208h (requires using LPC generic I/O) Reserved to Customer
				1010-1111 ← These values are reserved; do not use.

#### **UARTMODE1 – UART MODE REGISTER #1**

When the COM Transceiver Mode is set to RS422/485 (in the XCVRMODE register) and the RS-485 Automatic Direction Control is enabled (e.g., UART1\_485ADC set to '1') then the transceiver Tx output is enabled. When there are bytes to transmit and the transceiver Tx output is disabled (i.e., tri-stated) when there are no bytes to transmit.

When the COM Transceiver Mode is set to RS422/485 and Automatic Direction Control is disabled (e.g., UART1\_485ADC set to '0') then the UART is in Manual Direction Control mode and the transceiver Tx output enable is controlled by software using the RTS bit in the UART Modem Control Register.

RTS = '0' - Transceiver Tx output is enabled.

RTS = '1' - Transceiver Tx output is disabled (i.e., tri-stated).

**Warning:** Terminal software, expecting an RS-232 port, may set RTS to '1' and disable the transmitter when initializing an RS-422/485 port in Manual Direction Control mode. Application software that handles the RS-422/485 port should set RTS to '0' to enable transmitting when in Manual Direction Control mode.

Reset type is Platform.

Note: The values shown are for the default BIOS configuration.

Table 35: UARTMODE1 - UART MODE Register #1

Bits	Identifier	Access	Default	Description
7-6	Reserved	RO	00	Reserved. Writes are ignored; reads always return 0.
				COM2 RS-485 Automatic Direction Control:
				0 – Disabled
5	UART2_485ADC	R/W	0	1 – Enabled
				Note: Only enable in RS-485 mode. The COM2_MODE in XCVRMODE register must also be set to a '1'
				COM1 RS-485 Automatic Direction Control:
				0 – Disabled
4	UART1_485ADC	R/W	0	1 – Enabled
				<b>Note:</b> Only enable in RS-485 mode. The COM1_MODE in XCVRMODE register must also be set to a '1'
3-2	Reserved	RO	00	Reserved. Writes are ignored; reads always return 0.
				UART #2 Output Enable:
1	UART2_EN	R/W	1	0 – Tx and RTS outputs are disabled and UART I/O accesses are ignored.
				1 – Tx and RTS outputs are enabled
				UART #1 Output Enable:
0	UART1_EN	R/W	1	0 – Tx and RTS outputs are disabled and UART I/O accesses are ignored
				1 – Tx and RTS outputs are enabled

**Note:** When a UART is disabled, there will be no decoding of the UART I/O address range and any I/O activity will be passed to the ISA bus (this allows COM ports to be on the ISA bus if the FPGA UARTs are not used). This means that the UART must be enabled before accessing registers. If this is an issue, separate control bits can be added in UARTMODE2 or make one of the unused UART Base addresses a no-decode.

#### **UARTMODE2 – UART MODE REGISTER #2**

Standard software (the BIOS and the operating system) assumes the baud-rate clock is 1.8432 MHz and programs the divisors accordingly; however, a faster oscillator is needed for baud rates higher than 115,200.

The FAST\_MODE bit in this register is used to shift the divisor by 4 bits (multiply by 16) so that the legacy baud rate comes out correctly for the 16x UART clock. This bit must be set to use rates above 115,200 and may require custom software.

Reset type is Platform.

Note: The values shown are for the default BIOS configuration.

Table 36: UARTMODE2 - UART MODE Register #2

Bits	Identifier	Access	Default	Description
7-1	Reserved	RO	0000000	Reserved. Writes are ignored; reads always return 0.
			Sets how the baud-rate divisor for the 16550 UARTs are interpreted (applies to all ports):	
0	0 FAST_MODE	E R/W	0	0 – Divisor is multiplied by 16 (legacy mode for 1.8432 MHz clock)
				1 – Divisor is not modified (fast mode for 16x 1.8432 MHz clock)
				<b>Note:</b> This must be set to '1' to use baud rates above 115,200.

# **Programming Information for Hardware Interfaces**

## **Processor WAKE# Capabilities**

The following devices can wake up the processor using the PCIE\_WAKE# signal to the SoC:

- Ethernet port 1 controller
- Minicard (when always-powered)
- FPGA via either a Digital I/O or AUX connector GPIO

The following nine USB devices can wake up the processor using the in-band SUSPEND protocol:

- The 2 On-Board USB 3.0 Ports
- Any of the 4 CBR-4005 Paddleboard USB Ports
- Either of the 2 PCI104/Express "A" Connector (1-Blade) USB Ports
- Minicard (when always-powered)

# **Watchdog Timer**

A Watchdog timer is implemented within the FPGA. When triggered, the Watchdog timer can set a status bit, generate an interrupt and/or hit the push-button-reset. The Watchdog timer implements a 1-255 second timeout.

The Watchdog time out is set in an 8-bit register (WDT\_VAL). When the Watchdog is enabled, the WDT\_VAL will start to count down. If the Watchdog is enabled and whenever WDT\_VAL is zero, the Watchdog is triggered (so a non-zero value must be written before enabling the watchdog). Software must periodically write a non-zero value to WDT\_VAL to prevent this trigger. The value written should always be 1 greater than the desired timeout value due to a 0-1 second error band. Values written should be from 2-255 because a 1 could cause an immediate trigger); that is, the actual timeout is WDT\_VAL seconds with a -1 second to 0 second error band.

The Watchdog control/status register(s) have bits for the following:

- Watchdog enable/disable (disabled by default)
- Watchdog timeout status (This is cleared when the Watchdog is disabled or when a new value is written to WDT\_VAL. Writing WDT\_VAL would be the interrupt-acknowledge.)
- Watchdog interrupt IRQ select (from the same list of eight interrupts supported on the LPC SERIRQ)
- Interrupt enable
- Board reset enable (when set, the board will be reset when the Watchdog timer expires).

## Industrial I/O Functions and SPI Interface

The EPMe-42 employs a set of I/O registers for controlling external serial peripheral interface (SPI) devices. Refer to the descriptions of the SPICONTROL (page 14), SPISTATUS (page 15), and SPIDATA[0:3] (page 16) registers for more information.

The SPI bus specifies four logic signals:

- SCLK Serial clock (output from master)
- MOSI Master output, slave input (output from master)
- MISO Master input, slave output (output from slave)
- SS Slave select (output from master)

The EPMe-42 SPI implementation adds additional features, such as hardware interrupt input to the master. The master initiates all SPI transactions. A slave device responds when its slave select is asserted and it receives clock pulses from the master.

Slave selects are controlled in one of two modes: manual or automatic. In automatic mode, the slave select is asserted by the SPI controller when the most significant data byte is written. This initiates a transaction to the specified slave device. In manual mode, the slave select is controlled by the user and any number of data frames can be sent. The user must command the slave select high to complete the transaction.

The SPI clock rate can be software configured to operate at speeds between 1 MHz and 8 MHz. All four common SPI modes are supported through the use of clock polarity and clock phase controls.

To initiate an SPI transaction, configure SPI registers SPICONTROL and SPISTATUS as shown in Table 12 and Table 13 for the desired I/O device. For additional information on communicating with specific SPI devices, refer to their respective manufacturer's datasheets.

# **Programmable LED**

User I/O connector J4 includes an output signal for attaching a software controlled LED. Connect the cathode of the LED to J4, pin 16; connect the anode to +3.3 V. An on-board resistor limits the current when the circuit is turned on. A programmable LED is provided on the CBR-4005B paddleboard. Refer to the EPMe-42 Hardware Reference Manual for the location of the Programmable LED on the CBR-4005B paddleboard.

To switch the PLED on and off, refer to Table 4: PCR – Product Code and LED Register, on page 8.

\*\*\* End of document \*\*\*