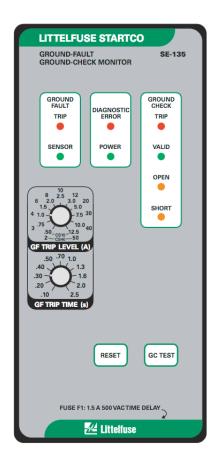
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## **SE-135 MANUAL**

# **GROUND-FAULT GROUND-CHECK MONITOR**

**REVISION 3-D-090816** 



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#### 1. GENERAL

The SE-135 is a microprocessor-based, combination ground-fault and ground-wire monitor for resistancegrounded systems. It has a switching power supply that accepts a wide range of ac and dc voltages, and its specifications apply over an industrial temperature range at high humidity. The SE-135 meets the IEEE surgewithstand-capability tests (oscillatory and fast transient) for protective relays and relay systems. normally open and normally closed contacts are provided for contactor control or for shunt or undervoltage operation in a breaker-trip circuit. All operating conditions are clearly annunciated and two Form C contacts are provided for remote indication. The SE-135 is housed in an anodized extruded-aluminum enclosure, and all connections are made with plug-in, wire-clamping terminal blocks. Provision is made for both panel and surface mounting.

The ground-fault circuit detects fundamental-frequency, zero-sequence current with a window-type current sensor and it verifies that the current sensor is connected and not shorted. A definite-time characteristic with 11 trip levels and 11 trip times allows coordination in virtually any resistance-grounded system. Although other current sensors may satisfy the verification circuit, only SE-CS10-series and SE-CS40-series sensors have characteristics that meet system specifications. Current-sensor verification can be disabled for a ground-check-only application.

The ground-check circuit has an open-circuit voltage of 30 Vdc, which is not a hazard to personnel, and it has an output drive current above 100 mA for optimum performance in slip-ring, commutated-load, and highinduced-ac applications. Features include an externally accessible ground-check fuse, a resistance-insertion test, 3-kV isolation between the ground-check loop and the monitor electronics, and a PPI-600V accessory for parallel-ground-path rejection. A PPI-600V will also eliminate intermachine arcing and prevent stray ac and dc currents from flowing in the monitored ground wire. Unlike ground-check circuits using other termination devices, and especially those with phase-reversal switches, a ground-check circuit using a termination device with a Zener characteristic is capable of loop measurements that are independent of current in the phase conductors. The SE-135 ground-check circuit recognizes the SE-TA12A-series 12-volt Zener characteristic as a valid end-of-line completion. This is the only passive characteristic that will satisfy the ground-check circuit's multi-level drive, allow induced currents to circulate in the ground-check loop, survive a phase-to-ground-check fault, and clamp the ground-check voltage during the fault. Although a standard 12-volt Zener diode may engage the SE-135's ground-check circuit, only an

SE-TA12A-series termination assembly has the compensation required to meet system specifications.

#### 2. OPERATION

# 2.1 GROUND-FAULT CIRCUIT 2.1.1 GF TRIP TIME SETTING

The ground-fault circuit has a definite-time characteristic with 11 settings from 0.1 to 2.5 seconds. Time-coordinated ground-fault protection requires the trip time to be longer than the trip time of downstream ground-fault devices.

#### 2.1.2 GF TRIP LEVEL SETTING

The trip level of the ground-fault circuit is switch selectable with 11 settings from 0.5 to 12.5 A for the SE-CS10-series CT and from 2 to 50 A for the SE-CS40-series CT. A minimum tripping ratio of five is recommended to achieve at least 80% winding protection, and this requires the trip level to be no more than 20% of the grounding-resistor let-through current. A ground-fault trip is latched, requiring a reset. A current-sensor failure will also cause a ground-fault trip. See Section 3.1.

If the SE-135 is operated in a ground-check-only application and an SE-CS10 is not connected, connect terminals 17 and 18 to disable sensor verification. See Fig. 1.

#### 2.2 GROUND-CHECK CIRCUIT

The ground-check loop consists of the outgoing ground-check conductor, quick-coupler connections, the SE-TA12A-series termination assembly, the SE-TA12A connection to equipment frame or ground bus, the ground-return path, and the SE-135 cable-ground-terminal connection to substation ground.

The SE-135 detects a valid ground-check loop when an SE-TA12A-series termination assembly is detected in the loop and loop resistance is less than 28 ohms (45 ohms for XGC option). The loop is not valid if open (or high resistance), or if the ground-check conductor is shorted to ground.

When the ground-check loop is valid, the SE-135 ground-check circuit can be tested by pressing the GC TEST button or by shorting GC TEST terminals 11 and 12. This test invalidates the loop by inserting 47 ohms (75 ohms for XGC option) in the ground-check loop and a trip should occur in less than 250 ms.

The ground-check circuit is usually operated in the non-latching mode; however, it can be operated in the latching mode by connecting terminals 14 and 15.

The ground-check circuit is protected by a 1.5-A time-delay fuse (F1).

If the SE-135 is used in a ground-fault-only application, an SE-TA12A must be connected to the ground-check and cable-ground terminals to validate the ground-check circuit. See Fig. 1.



The typical maximum distance of a trailing cable is 5.0 km (3.1 miles) for the standard model and up to 10 km (6.3 miles) for the XGC option. Several factors may limit the maximum distance of the cable, including the ground-check wire gauge, and induced ac current in the ground-check loop.

#### 2.3 RESET

All ground-fault trips are latching and ground-check trips can be latching or non-latching. To reset ground-fault trips or latching ground-check trips, press the RESET button or connect the RESET terminals 9 and 10. See Fig. 1.

Cycling the supply voltage will also reset ground-fault trips; however, if the ground-check circuit is configured for latching fail-safe operation, the ground-check circuit will trip when supply voltage is applied.

The single-shot reset circuit responds only to a momentary closure; a jammed or shorted button will not maintain a reset signal. The front-panel RESET button is inoperative when remote-reset terminals 9 and 10 are connected. See Section 4.5.

#### 2.4 TRIP RELAY

Isolated, normally open (Trip A, terminals 24 and 25) and normally closed (Trip B, terminals 22 and 23) contacts are provided for use in a contactor- or breaker-control circuit. With no connection between terminals 12 and 13, the SE-135 trip relay operates in the fail-safe mode. This mode is used with undervoltage devices where the trip relay energizes and its normally open contact closes if the ground-fault and ground-check circuits are not tripped. This mode is recommended because:

- Undervoltage devices release if supply voltage fails.
- Undervoltage ground-check circuits do not allow the power circuit and open cable couplers to be energized until the ground-check loop is verified.

The fail-safe mode of operation of the SE-135 trip relay can be used for shunt-trip circuits with a stored-energy trip source. In this case, the normally closed trip contact is used—the contact opens when the SE-135 is energized and the ground-fault and ground-check circuits are not tripped. Care must be taken to ensure safe and correct operation during power up and power down.

Connect terminals 12 and 13 for non-fail-safe trip relay operation with shunt-trip devices. In this mode, the normally open trip contact is used—the trip contact is closed when a ground-fault or ground-check trip occurs.

Shunt-trip circuits are not fail-safe and are not recommended because:

 Shunt-trip devices do not operate if supply voltage fails.  Shunt-trip ground-check circuits allow the power circuit and open cable couplers to be energized for a short interval after supply voltage is applied.

**CAUTION:** The SE-135 is not a lock-out device. Follow lock-out procedures for maintenance.

#### 2.5 NETWORK COMMUNICATIONS

An IEEE 802.3 port with Modbus<sup>®</sup> TCP Ethernet protocol is available.

The SE-135 default IP address is 10.0.0.1. Use SE-MON-GFGC to change the IP address, monitor connected SE-135 units, and to issue remote commands. SE-MON-GFGC can be downloaded from www.littelfuse.com/relayscontrols.

If the computer running SE-MON-GFGC has more than one active network connection, SE-MON-GFGC may not detect the SE-135. Ensure SE-MON-GFGC is not blocked by Windows Firewall by adding it to the Firewall Exceptions list in the Windows Control Panel.

On start-up SE-MON-GFGC scans the network for SE-135 units and displays them in a list. Select one from the list and click "Edit" to change the IP address, subnet mask, or description. When selecting an IP address, ensure it is not already in use. Click "Apply" to save the changes. SE-MON-GFGC will pause for five seconds and scan the network again.

To view the status of an SE-135, select the unit and click "Monitor". If a warning appears, the SE-135 may have been set to an IP address that is not accessible by the network.

Table 1 shows the SE-135 coil addresses. Table 2 provides the holding registers in 16-bit format.

A remote reset can be generated by writing DO1 high for one second and then writing it back to low.

TABLE 1. COIL ADDRESS

TIBLE 1: COLL TIBBRESS				
COIL	DESCRIPTION	Name	ATTRIBUTE	
ADDRESS				
00001	GC Status	DI0	Read	
00002	GF Status	DI1	Read	
00003	Trip Relay	DI2	Read	
00018	Remote Reset	DO1	Read/Write	

TABLE 2. HOLDING REGISTER ADDRESS

REGISTER ADDRESS	DESCRIPTION	ATTRIBUTE
40301	DI0 – DI11	Read
40303	DO0 – DO5	Read/Write



#### 3. INDICATION

#### 3.1 GROUND FAULT

A red TRIP LED indicates a ground-fault trip and the remote-indication relay GF is energized when the ground-fault circuit is not tripped (fail-safe indication-contact operation). A green SENSOR LED indicates a current sensor is correctly connected. If the SE-CS10- or SE-CS40-series current sensor is disconnected or shorted, the green LED will go out and the ground-fault circuit will trip. If the sensor fault is intermittent, the ground-fault circuit will trip and the green LED will flash to indicate that the trip was initiated by a sensor fault.

**Note:** The SE-CS10- and SE-CS40-series current sensors are 600-V-rated current transformers. When system voltage is above 600 V, ensure conductors passed through the sensor window are insulated to system voltage.

#### 3.2 Power

The green POWER LED indicates that the internal power supply is on.

#### 3.3 DIAGNOSTIC ERROR

The red DIAGNOSTIC ERROR LED indicates that an internal error caused the SE-135 to trip. Return the SE-135 to the factory if a reset does not clear the trip.

Induced ac current in the ground-check loop can cause the LED to flicker. This is a normal condition and does not indicate a diagnostic error; the ground-check monitoring circuit is not affected.

#### 3.4 GROUND CHECK

A red TRIP LED indicates a ground-check trip. A green VALID LED indicates a valid ground-check loop and the remote-indication relay GC is energized when the ground-check loop is valid (fail-safe indication-contact operation). Two yellow LED's indicate the status of an invalid ground-check loop. OPEN indicates the loop resistance exceeds the trip resistance and SHORT indicates the ground-check conductor is shorted to the ground conductor. A flashing yellow LED indicates the corrected cause of a latched ground-check trip.

#### 4. Installation

### 4.1 GENERAL

This ground-fault ground-check monitoring system consists of an SE-135 Monitor, an SE-CS10- or SE-CS40-series Current Sensor, and an SE-TA12A-series Termination Assembly connected as shown in Fig. 1. If required, remote indication and reset can be implemented with standard pilot devices, or with an RK-132 Remote-Indication-and-Reset Kit.

#### 4.2 MONITOR

Each SE-135 is packaged with both panel- and surface-mounting hardware.

Outline and panel-cutout dimensions for the SE-135 are shown in Fig. 2. To panel mount the SE-135, insert it through the panel cutout and secure it with the four supplied 8-32 locknuts and flat washers.

If an optional SE-IP65CVR-G is used, follow the included installation instructions. See Figs. 4 and 5.

All connections to the SE-135 are made through plugin, wire-clamping terminal blocks for 24 to 12 AWG (0.2 to 2.5 mm<sup>2</sup>) conductors. Each plug-in terminal block can be secured to the monitor by two captive screws for reliable connections in high-vibration applications.

Outline dimensions and mounting details for surface mounting an SE-135 are shown in Fig. 3. Fasten the SE-134-SMA Surface-Mount Adapter to the mounting surface and make connections to the adapter terminal blocks. Follow the instructions in Fig. 3 to install or remove the SE-135.

Use terminal 1 (L1) as the line terminal on ac systems or the positive terminal on dc systems. Use terminal 2 (L2/N) as the neutral terminal on ac systems or the negative terminal on dc systems.

**NOTE:** On revision 4 and newer units, terminal 3 (SPG) is internally connected to terminal 4. For these units an external terminal-3-to-terminal-4 connection is not required, nor is it necessary to remove the terminal-3 connection for dielectric-strength testing.

#### 4.3 CURRENT SENSORS

Outline dimensions and mounting details for the SE-CS10- and SE-CS40-series current sensors are shown in Fig. 6. Pass only phase conductors through the sensor window as shown in Fig. 1. If a shield, ground, or ground-check conductor enters the sensor window, it must be returned through the window before it is terminated. Connect the current sensor to terminals 16 and 17. Ground terminal 17. Current-sensor primary and secondary connections are not polarity sensitive. See Section 4.7.

#### 4.4 TERMINATION ASSEMBLY

Outline dimensions and mounting details for the SE-TA12A, SE-TA12A-WL, and SE-TA12ASF-WL are shown in Figs. 7 and 8. Install the SE-TA12A at the load to complete the ground-check loop as shown in Fig. 1. Connect terminal G of the SE-TA12A to the equipment frame so that the ground-conductor-to-equipment-frame connection will be included in the monitored loop.

#### 4.5 REMOTE OPERATION

Remote indication contacts and a reset input are provided as shown in Fig. 1.

The optional RK-132 Remote Kit is shown in Fig. 9. Connect terminals of the green ground-check indicator to



SE-135 terminals 26 and 27 and the red ground-fault indicator to terminals 19 and 21. For remote reset, connect the normally open push-button switch across terminals 9 and 10.

#### 4.6 PARALLEL-PATH ISOLATION

A PPI-600V can be used for parallel-path rejection. A PPI-600V will also eliminate inter-machine arcing and prevent stray ac and dc currents from flowing in

the monitored ground wire. See Figs. 10 and 11. See Technical Note GC-10 "Parallel Path Isolator" at www.littelfuse.com/relayscontrols, or contact Littelfuse Startco for application details.

#### 4.7 FERRITE PLACEMENT

A ferrite kit is included with CE-compliant options only. Where CE compliance is desired, install each ferrite as shown in Fig. 12. If a current sensor is used, connect the shield wire as shown in Fig. 13.

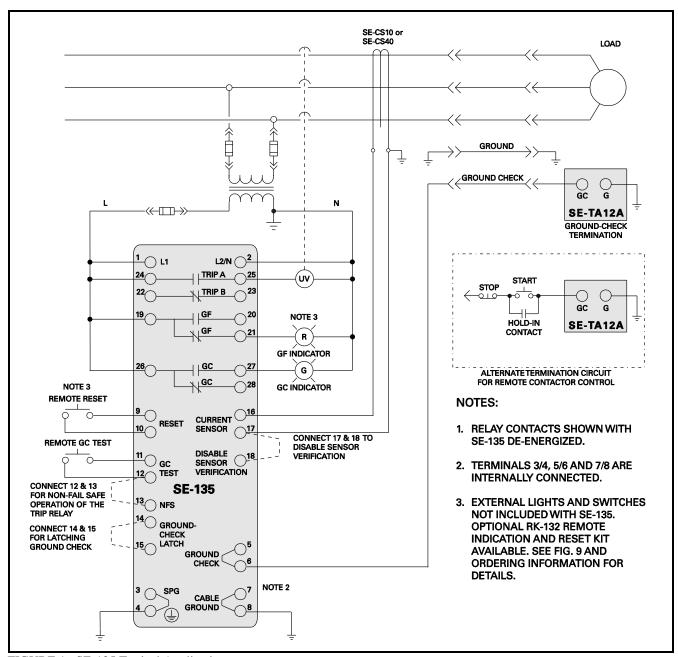


FIGURE 1. SE-135 Typical Application.



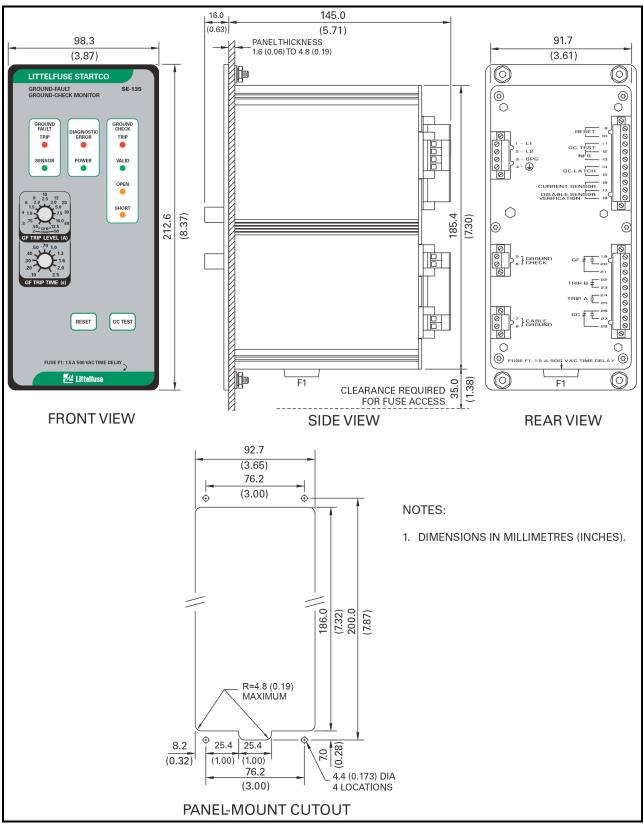


FIGURE 2. SE-135 Outline and Panel-Mounting Details.



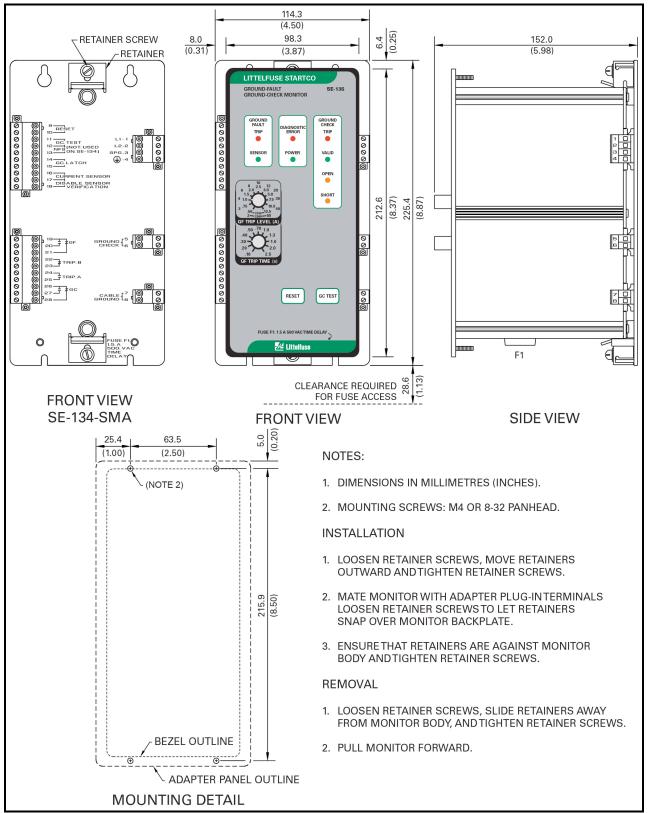


FIGURE 3. SE-134-SMA Surface Mount Adapter and SE-135 Surface-Mounting Details.



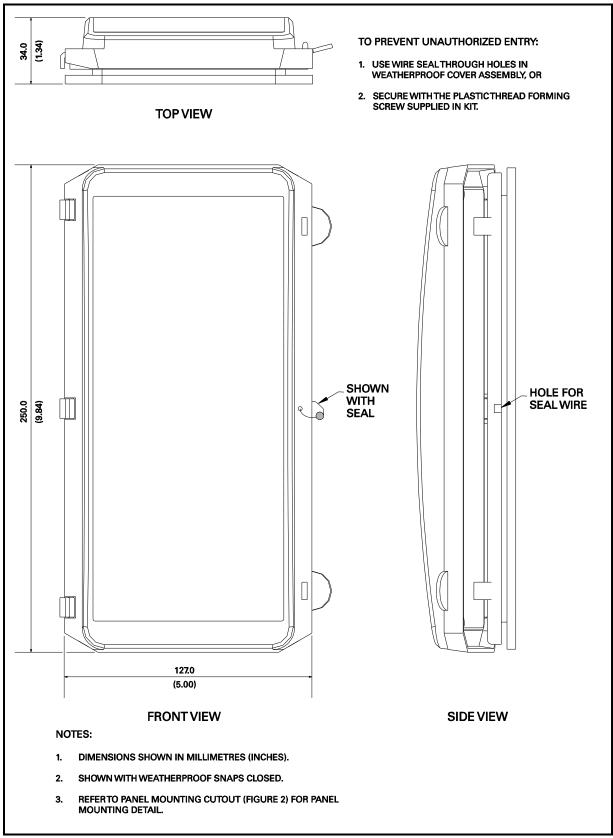


FIGURE 4. SE-IP65CVR-G Weatherproof Cover Outline.



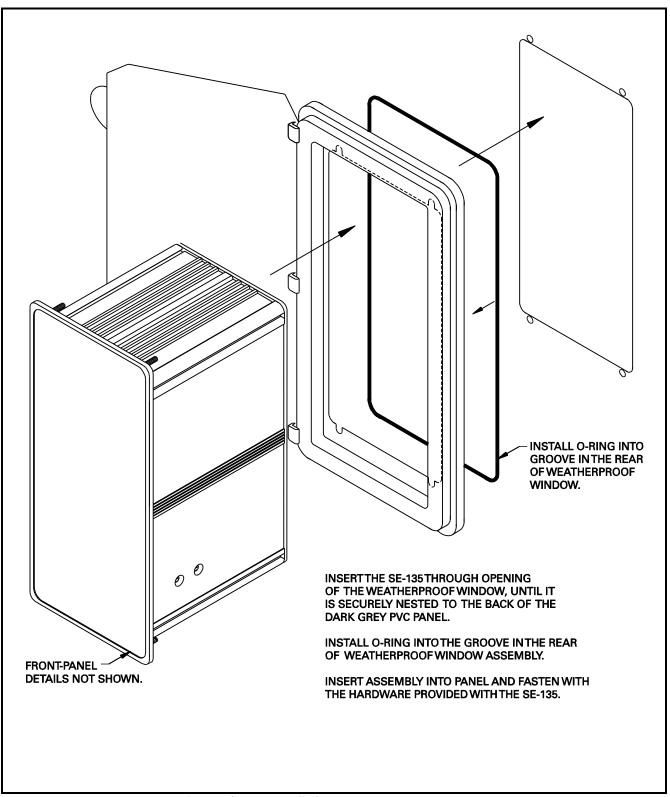


FIGURE 5. SE-IP65CVR-G Weatherproof Cover Installation.



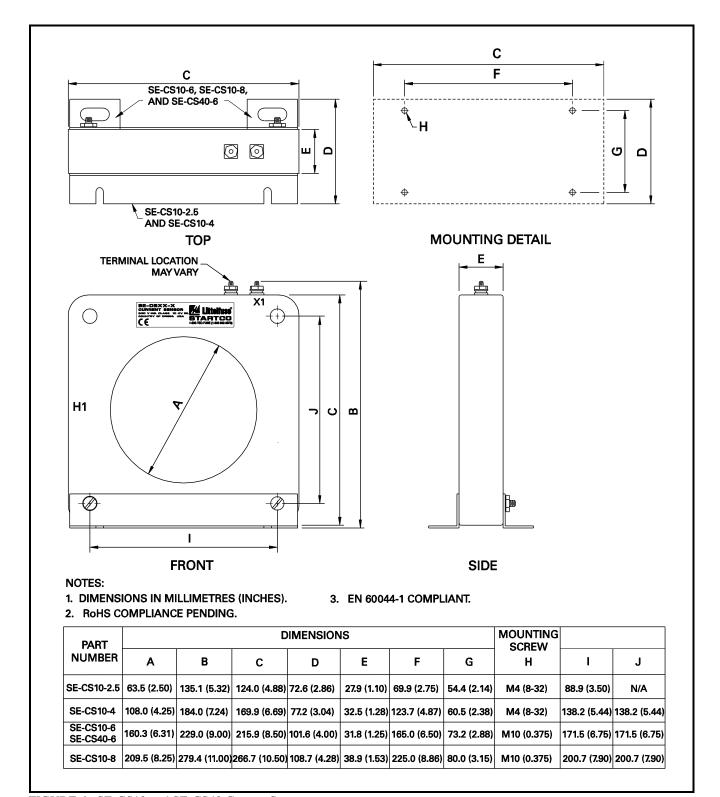


FIGURE 6. SE-CS10 and SE-CS40 Current Sensors.



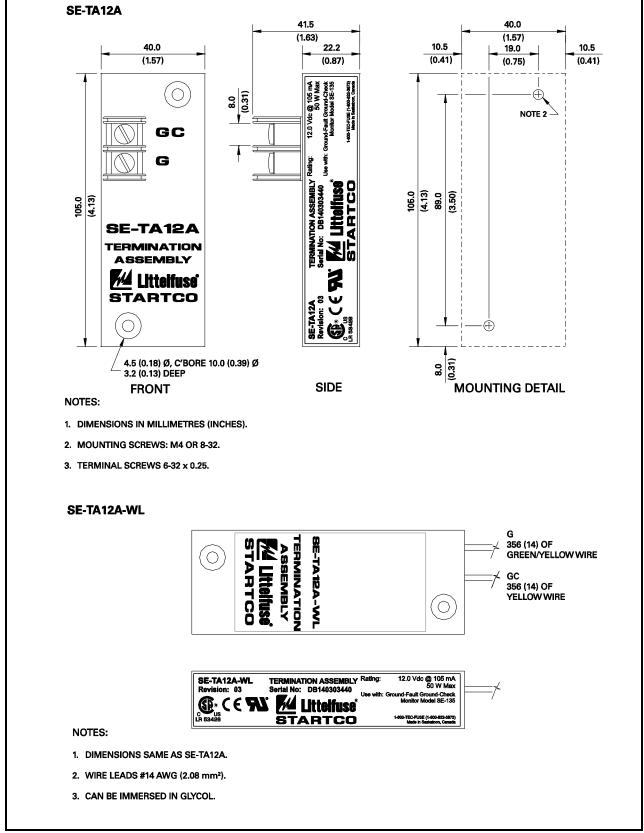


FIGURE 7. SE-TA12A and SE-TA12A-WL Termination Assemblies.



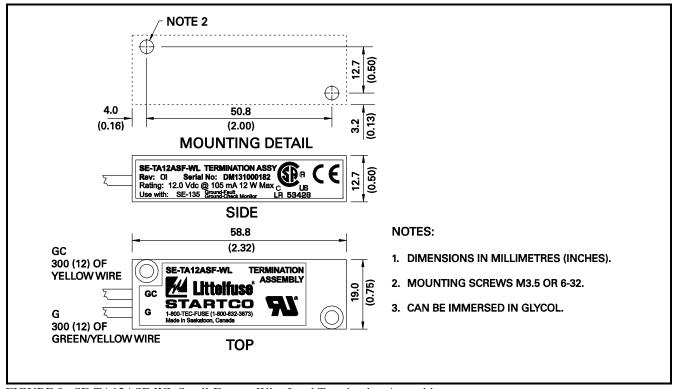


FIGURE 8. SE-TA12ASF-WL Small-Format-Wire-Lead Termination Assembly.

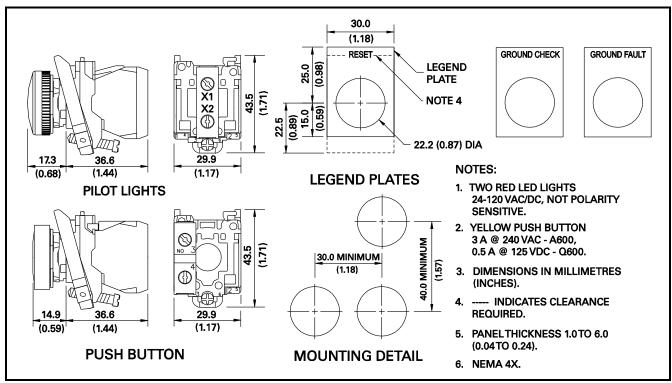


FIGURE 9. RK-132 Remote Indication and Reset Kit.



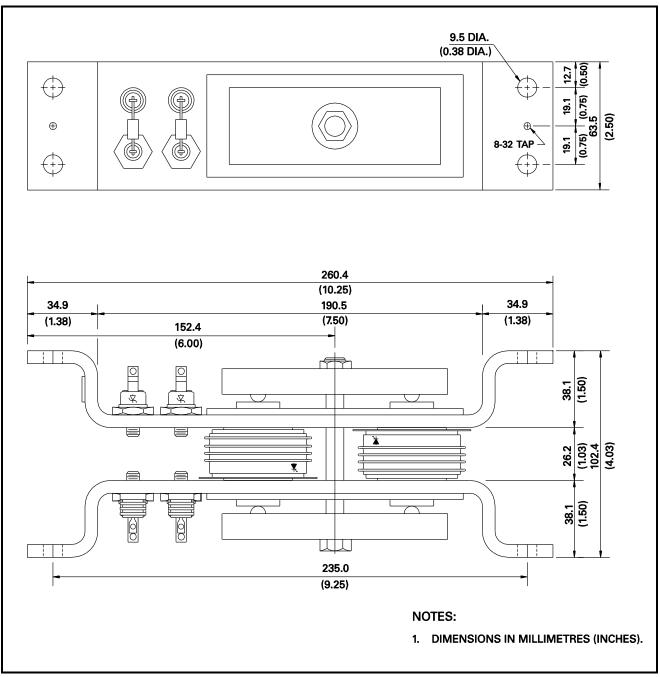
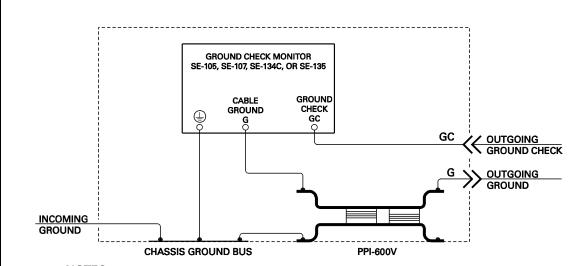


FIGURE 10. PPI-600V Parallel-Path Isolator.



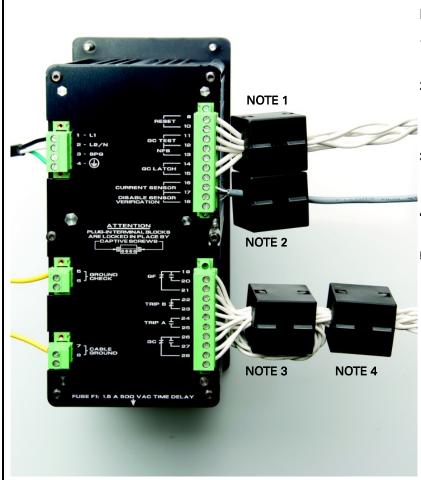


#### NOTES:

- 1. THE PARALLEL-PATH ISOLATOR IS NOT POLARIZED. EITHER FLANGE CAN BE CONNECTED TO CHASSIS.
- 2. THE OUTGOING GROUND MUST BE ISOLATED FROM THE CHASSIS GROUND BUS. IF A FLANGE-MOUNTED RECEPTACLE IS USED, VERIFY THAT THE FLANGE IS ISOLATED FROM THE GROUND PIN, AND
  - USE A MATING PLUG WITH A NON-METALLIC HOUSING, OR
  - ISOLATE THE FLANGE FROM THE CHASSIS IF THE MATING PLUG HAS A METALLIC HOUSING.
- 3. CABLE PLUGS AND RECEPTACLES WITH GROUNDED METAL HOUSING MUST BE ISOLATED FROM GROUNDTO PREVENT PARALLEL GROUND PATHS.
- 4. FOR SYSTEMS ABOVE 600 VAC, CONNECT A V131DA40 MOV ACROSSTHE PPI-600V.

FIGURE 11. PPI-600V Typical Installation.





#### **NOTES:**

- 1. PASS WIRES FROMTERMINALS 9TO 15 THROUGH A FERRITE.
- 2. PASSTHE SHIELDED CABLE FROM TERMINALS 16TO 17 THROUGH A FERRITE. CONNECT THE SHIELDTO CHASSIS AS SHOWN IN FIG. 13.
- 3. DOUBLE LOOP THE WIRES FROM TERMINALS 19 TO 28 THROUGH A FERRITE.
- 4. PASS WIRES FROM FERRITE (NOTE 3) THROUGH A SECOND FERRITE.
- 5. ALL FERRITES ARE LAIRD TECHNOLOGIES 28A2024-0A2 AND ARE ROHS COMPLIANT.

FIGURE 12. SE-135 with Ferrites Installed.

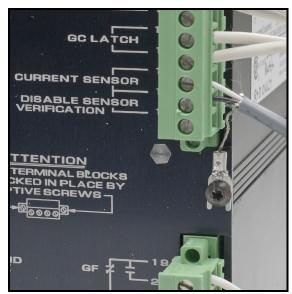


FIGURE 13. Current Sensor Shield Connection.



#### Trip Mode .....Latching or Non-Latching 5. TECHNICAL SPECIFICATIONS 5.1 SE-135 Trip Relay: Supply: CSA/UL Contact Rating .....8 A Resistive 250 Vac, Option 0......25 VA, 120-240 Vac 5 A 30 Vdc, (+10, -45%), 50-400 Hz; 0.25 HP, 15 W, 110-250 Vdc **B300** Pilot Duty (+10, -25%)Supplemental Contact Ratings: Make/Carry (0.2 s) ......30 A (+50, -25%);Break dc ......75 W Resistive, 20 VA, 48 Vac 35 W Inductive (L/R < 0.04) (+10, -55%), 50-100 Hz Break ac......2,000 VA Resistive, Ground-Fault Circuit: 1.500 VA Inductive Digital Filter......50 to 60 Hz, Bandpass (PF > 0.4)3 dB Frequency Response ... 30 to 90 Hz Subject to maximums of 8 A and 250 V (ac or dc) Trip-Level Settings: Contact Configuration......Isolated N.O. and N.C. SE-CS10-x ......50, .75, 1.0, 1.5, 2.0, 2.5, Contacts 3.0, 5.0, 7.5, 10.0,and Operating Mode ......Fail-Safe or 12.5 A Non-Fail-Safe SE-CS40-x ......2, 3, 4, 6, 8, 10, 12, 20, 30, Maximum Switching 40, and 50 A Capacity ......Fig. 14 Remote-Indication Relays: 1.0, 1.3, 1.6, 2.0, and CSA/UL Contact Rating .....8 A Resistive 250 Vac, 2.5 s8 A 30 Vdc Thermal Withstand: Supplemental Contact Ratings: SE-CS10-x ......150 A Continuous Make/Carry (0.2 s) ......20 A 1,000 A for 2.5 s Break dc .....50 W Resistive, (Ground-Fault Current) 25 W Inductive (L/R < 0.04) SE-CS40-x ......600 A Continuous Break ac.....2,000 VA Resistive, 4,000 A for 2.5 s 1,500 VA Inductive (Ground-Fault Current) (PF > 0.4)Sensor Lead Resistance......2 Ω maximum Subject to maximums of 8 A and 250 V (ac or dc) Trip-Level Accuracy: Contact Configuration......N.O and N.C. (Form C) SE-CS10-x.....5% or 0.1 A Operating Mode ......Fail-Safe SE-CS40-x.....5% or 0.4 A Maximum Switching Trip-Time Accuracy.....+50, -15 ms Capacity ......Fig. 15 Sensor Verification ......Enabled or Disabled Sensor-Fault Detection......Open and Short Trip Reset .....Front-Panel Button and Trip Mode .....Latching Remote, N.O. Contact Ground-Check Circuit: Open-Circuit Voltage ......30 Vdc Terminal Block Rating ......10 A, 300 Vac, Output Impedance ......136 $\Omega$ 12 AWG (2.5 mm<sup>2</sup>) Loop Current ......105 mA Induced-ac Withstand .......60 Vac Continuous, PWB Conformal Coating ......MIL-1-46058 qualified, 120 Vac for 10 s, UL OMJU2 recognized 250 Vac for 0.25 s Pull-in Time .....≤ 1.5 s Trip Resistance: Mounting Configuration ......Panel Mount and Surface Mount XGC Option ......45 $\Omega \pm 10\%$ Dimensions: Trip Time: Height......213 mm (8.4") Standard at 50 $\Omega$ ......220 $\pm$ 30 ms XGC Option at 75 $\Omega$ ......220 $\pm$ 30 ms Short Detection ......Yes Isolation...... 3 kV, 60 Hz, 1 s Shipping Weight ......2.3 kg (5.1 lb) Test.....Front-Panel Button and Environment: Remote, N.O. Contact Fuse Rating (F1) ......1.5 A, 500 Vac, Operating Temperature......-40 to 60°C (-40 to 140°F) Storage Temperature.....-55 to 80°C (-67 to 176°F) Time Delay Humidity ......85% Non-Condensing Fuse Part Number .....FNQ 1½ Buss Fusetron



# SE-135 Ground-Fault Ground-Check Monitor

IP Rating		CertificationCSA Canada and USA
0 W/4 . 1	mounted, IP20 otherwise	C
Surge Withstand		c us UL Listed
	(Oscillatory and Fast	
EMC Tests:	Transient)	Ground Fault Sensing and Releying Equipment 4FX9 E340889 Australia
	dance with EN 60255-26:2009.	4FX9 E340889 Australia
verification tested in accord	dance with EN 00233-20.2009.	^
Radiated and Conducted		
Emissions	CISPR 22:2008-09	CE, European Union
	Class A	C€
		FCC
Current Harmonics and		
Voltage Fluctuations	IEC 61000-3-2	1 😉
	and IEC 61000-3-3	To: CSA C22.2 No. 14 Industrial Control Equipment
	Class A	UL 508 Industrial Control Equipment
		UL 1053 Ground Fault Sensing and Relaying
Electrostatic Discharge		Equipment
	± 6 kV contact discharge	Australia, Regulatory Compliance Mark (RCM)
	(direct and indirect)	CE Low Voltage Directive IEC 61010-1:2010 (3 <sup>rd</sup> Edition)
	± 8 kV air discharge	FCC CFR47, Part 15, Subpart B,
Radiated RF Immunity	IEC 61000 4 3	Class A – Unintentional Radiators
Radiated KI Illinumity	10 V/m, 80-1,000 MHz,	Class 11 Chine Intolia Radiators
	80% AM (1 kHz)	ComplianceRoHS Pending
	10 V/m, 1.0 to 2.7 GHz,	g
	80% AM (1 kHz)	5.2 CURRENT SENSORS
	(/	Environment:
Fast Transient	IEC 61000-4-4	Operating Temperature40 to 60°C (-40 to 140°F)
	Class A: ± 4 kV (on AC	Storage Temperature55 to 80°C (-67 to 160°F)
	mains and I/O lines)	
		SE-CS10-2.5:
Surge Immunity		Current Ratio1,000:5 A
	Zone B	Insulation600-V Class
	± 1 kV differential mode	Window Diameter
	± 2 kV common mode	Shipping Weight690 g (1.5 lb)
Conducted RF Immunity.	IEC 61000 4 6	SE-CS10-4:
Conducted KI Infindinty.	10 V, 0.15-80 MHz,	SE-CS10-4: Current Ratio1,000:5 A
	80% AM (1 kHz)	Insulation
	00 % 7HWI (1 KHZ)	Window Diameter
Magnetic Field		Shipping Weight
Immunity	IEC 61000-4-8	
•	50 Hz and 60 Hz	SE-CS10-6:
	30 A/m and 300 A/m	Current Ratio1,000:5 A
		Insulation600-V Class
Power Frequency		Window Diameter160 mm (6.3")
	Zone A: differential mode	Shipping Weight2.2 kg (4.8 lb)
	150 Vrms	
	Zone A: common mode 300 Vrms	
	200 11119	
1 MHz Burst	IEC 61000-4-18	
	± 1 kV differential mode	
	(line-to-line)	
	25 kV samman mada	

± 2.5 kV common mode



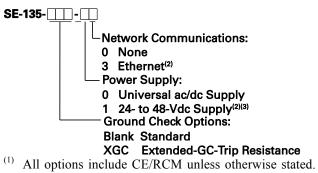
Power Rating.....50 W

# SE-135 Ground-Fault Ground-Check Monitor

SE-CS10-8:		Wire Leads	$14 \text{ AWG} (2.08 \text{ mm}^2)$
Current Ratio	1 000·5 A		256 (1.43)
Insulation		Dimensions	105 v 40 v 22 2 mm
Window Diameter		Dimensions	(4.13 x 1.57 x 0.87")
		Shipping Weight	
Shipping Weight	2.2 Kg (4.8 lb)	Snipping weight	300 g (0.7 lb)
SE-CS40-6:		SE-TA12ASF-WL:	
Current Ratio	800:1 A	Characteristic	12-V Zener, Temperature
Insulation	600-V Class		Compensated
Window Diameter		Circuit Type	High-Current Shunt Regulator
Shipping Weight	1.8 kg (4.0 lb)	Reverse Voltage	12 ±0.03 Vdc @ 100 mA
11 0 0		Forward Voltage	0.5 ±0.1 Vdc @ 100 mA
Certification	CE <sup>(1)</sup> Furopean Union		40 to 60°C (-40 to 140°F)
Certification		Current Range	
	CE	Maximum Clamping	
			55 V @ 250 A, 5x20 \(\mu\)s Pulse
Compliance	IEC 60044-1	Power Rating	
1	RoHS Pending	Wire Leads	
		Wife Deads	300 mm (11.8")
NOTES:		Dimensions	
(1) When connected to an SE	1.135	Difficusions	$(2.32 \times 0.75 \times 0.5^{\circ})$
when connected to an SE	7-155.	Shipping Weight	,
5.3 TERMINATION ASSEMBI	LIES	Shipping Weight	тэ g (0.1 10)
SE-TA12A:			
Characteristic	12-V Zener, Temperature	Certification	_
	Compensated		© LR 53428 C US
Circuit Type	High-Current Shunt		C US
	Regulator		UL Listed
Reverse Voltage	12 ±0.03 Vdc @ 100 mA		(VL) LISTED Ground Fault Sensing
Forward Voltage	0.5 ±0.1 Vdc @ 100 mA		LISTER Ground Fault Sensing and Relaying Equipment 4FX9 E340888 CE <sup>(1)</sup> , European Union
Operating Temperature	40 to 60°C (-40 to 140°F)		
Current Range	2 mA to 25 A		CE
Maximum Clamping		NOTES:	
Voltage	55 V @ 250 A,	(1) When connected to an SE	S-135
_	5x20 μs Pulse	When connected to an SI	1133.
Power Rating	50 W		
Screw Terminal			
Dimensions	105 x 40 x 41.5 mm		
	(4.13 x 1.57 x 1.63")		
Shipping Weight			
11 8 8			
SE-TA12A-WL:			
Characteristic	12-V Zener, Temperature		
	Compensated		
Circuit Type	High-Current Shunt		
-	Regulator		
	12 ±0.03 Vdc @ 100 mA		
	0.5 ±0.1 Vdc @ 100 mA		
Operating Temperature	40 to 60°C (-40 to 140°F)		
Current Range			
Maximum Clamping			
Voltage	55 V @ 250 A,		
-	5x20 μs Pulse		



### 6. ORDERING INFORMATION(1)



- CE/RCM models include a ferrite kit.
- CE/RCM not available.
- (3) Not available with Ethernet network communications option.

Ground-Check Termination:	
SE-TA12A	50-W Termination
	Assembly with Screw
	Terminals
SE-TA12A-WL	50-W Termination
	Assembly with Wire
	Leads
SE-TA12ASF-WL	12-W Small-Format
	Termination Assembly

Current Sensors:	
SE-CS10-2.5	Current Sensor,
	63 mm (2.5") window
SE-CS10-4	Current Sensor,
	108 mm (4.2") window
SE-CS10-6	Current Sensor,
	160 mm (6.3") window
SE-CS10-8	Current Sensor,
	209 mm (8.2") window
SE-CS40-6	Current Sensor,
	160 mm (6.3") window

with Wire Leads

3E-C340-0	Current Sensor,
	160 mm (6.3") window
Parallel Path Isolator	
PPI-600V	For system voltages up to
	600 Vac

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#### 7. WARRANTY

The SE-135 Ground-Fault Ground-Check Monitor is warranted to be free from defects in material and workmanship for a period of five years from the date of purchase.

Littelfuse Startco will (at Littelfuse Startco's option) repair, replace, or refund the original purchase price of an SE-135 that is determined by Littelfuse Startco to be defective if it is returned to the factory, freight prepaid, within the warranty period. This warranty does not apply to repairs required as a result of misuse, negligence, an accident, improper installation, tampering, or insufficient Littelfuse Startco does not warrant products repaired or modified by non-Littelfuse Startco personnel.



#### 8. TEST PROCEDURES

#### 8.1 GROUND-CHECK TRIP TESTS

#### 8.1.1 LATCHING GROUND-CHECK TRIP TEST

Connect the monitor, current sensor and termination assembly as shown in Fig 16. Connect terminals 14 and 15 for latching operation. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on.

Open the ground-check loop by removing either the GC or G connection between the monitor and the termination assembly (pressing the faceplate GC TEST button will also perform an open-ground-check test). The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the OPEN LED's will be on.

Reconnect the ground-check loop. The VALID and TRIP LED's will be on and the OPEN LED will be flashing. The TRIP contacts (terminals 22-23 and 24-25) will remain latched and ground-check indication contacts (terminals 26-27 and 26-28) will change state.

Reset the monitor.

Short the ground-check loop by connecting G to GC. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the SHORT LED's will be on.

Remove the short from G to GC. The VALID and TRIP LED's will be on and the SHORT LED will be flashing. The TRIP contacts (terminals 22-23 and 24-25) will remain latched and ground-check indication contacts (terminals 26-27 and 26-28) will change state.

Reset the monitor.

#### 8.1.2 Non-Latching Ground-Check Trip Test

Connect the monitor, current sensor and termination device as shown in Fig. 16. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on.

Open the ground-check loop by removing either the GC or G connection between the monitor and the termination assembly (pressing the faceplate GC Test button will also perform an open circuit test). The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the OPEN LED's will be on.

Reconnect the ground-check loop. The monitor will reset.

Short the ground-check loop by connecting G to GC. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the SHORT LED's will be on.

Remove the short from G to GC. The monitor will reset.

#### 8.2 TRIP RELAY FAIL-SAFE MODE TEST

Connect the monitor, current sensor and termination device as shown in Fig. 16. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on. The output contacts between terminals 22 and 23 will be open and between 24 and 25 will be closed.

Remove the supply voltage. The output contacts between terminals 22 and 23 will close and the output contacts between terminals 24 and 25 will open.

#### 8.3 CURRENT-SENSOR-VERIFICATION TEST

Connect the monitor, current sensor and termination device as shown in Fig. 16. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on.

Open the current-sensor circuit by disconnecting one of the sensor leads. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-fault indication contacts (terminals 19-20 and 19-21) will change state. The GROUND FAULT TRIP LED will be on and the SENSOR LED will be off.

Reconnect the current sensor. The GROUND FAULT TRIP LED will stay on and the SENSOR LED will flash. The output contacts will remain latched.

Reset the monitor.

Short the current sensor by connecting terminals 16 and 17. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-fault indication contacts (terminals 19-20 and 19-21) will change state. The GROUND FAULT TRIP LED will be on and the SENSOR LED will be off.

Remove the short from terminals 16 and 17. The GROUND FAULT TRIP LED will stay on and the SENSOR LED will flash. The output contacts will remain latched.

Reset the monitor.

# 8.4 SE-TA12A-SERIES TERMINATION ASSEMBLY TESTS

Apply 24 Vdc across the series combination of a 100- $\Omega$ , 5-W current-limiting resistor and the termination assembly, as shown in Fig. 17. In the reverse biased test, the voltage should be 12 V across the termination assembly terminals. In the forward biased test, the voltage across the termination assembly terminals should be between 0.3 and 0.9 V.



#### 8.5 GROUND-FAULT PERFORMANCE TEST

To meet the requirements of the National Electrical Code (NEC), as applicable, the overall ground-fault protection system requires a performance test when first installed. A written record of the performance test is to be retained by those in charge of the electrical installation in order to make it available to the authority having jurisdiction. A test-record form is provided for recording the date and the final results of the performance tests.

The following ground-fault system tests are to be conducted by qualified personnel:

- a) Evaluate the interconnected system in accordance with the overall equipment manufacturer's detailed instructions.
- b) Verify proper location of the ground-fault current sensor. Ensure the cables pass through the ground-fault-current-sensor window. This check can be done visually with knowledge of the circuit. The connection of the current-sensor secondary to the SE-135 is not polarity sensitive.
- c) Verify that the system is correctly grounded and that alternate ground paths do not exist that bypass the current sensor. High-voltage testers and resistance bridges can be used to determine the existence of alternate ground paths.
- d) Verify proper reaction of the circuit-interrupting device in response to a simulated or controlled ground-fault current. To simulate ground-fault current, use CT-primary current injection. Fig. 14 shows a test circuit using Littelfuse Startco Ground-Fault-Relay Test Units. The SE-400 has a programmable output of 0.5 to 9.9 A for a duration of 0.1 to 9.9 seconds. Set the test current to 120% of GF TRIP LEVEL. The SE-100T provides a test current of 0.65 or 2.75 A for testing 0.5- and 2.0-A trip levels. Inject the test current through the current-sensor window for at least 2.5 seconds. Verify that the circuit under test has reacted properly. Correct any problems and re-test until the proper reaction is verified.
- e) Record the date and the results of the test on the attached test-record form.

TABLE 3. GROUND-FAULT-TEST RECORD

DATE TABLE 3. C	TEST RESULTS
	by the authority having jurisdiction

Retain this record for the authority having jurisdiction.



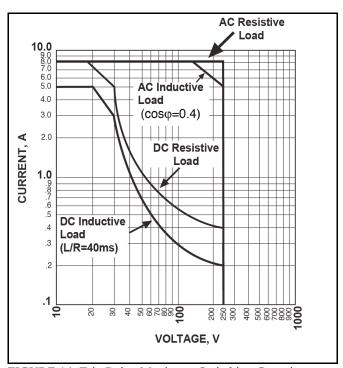


FIGURE 14. Trip Relay Maximum Switching Capacity.

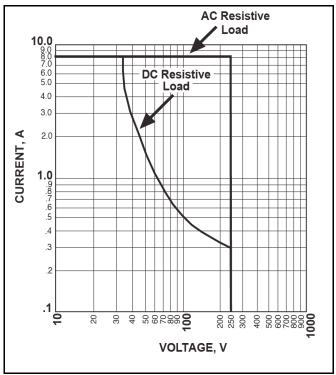


FIGURE 15. Remote-Indication Relays GC and GF Maximum Switching Capacity.



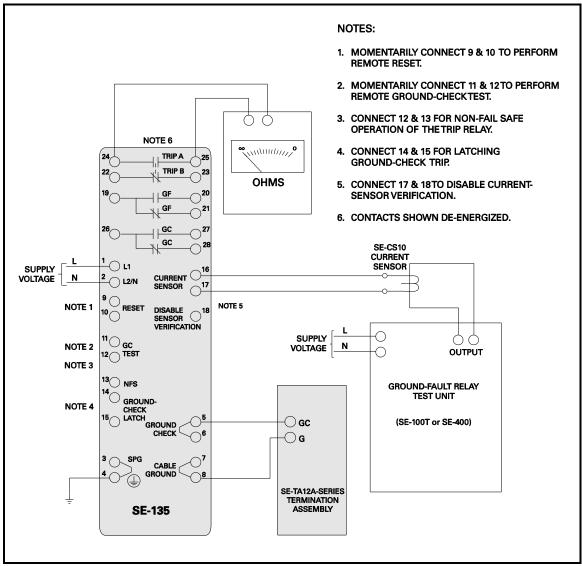


FIGURE 16. Ground-Fault-Test Circuit.

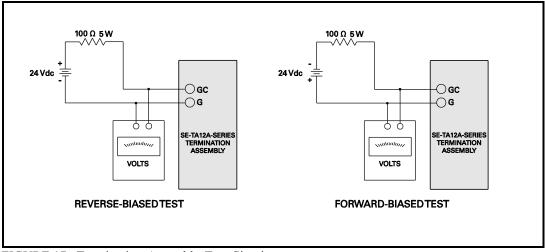


FIGURE 17. Termination-Assembly-Test Circuits.



## APPENDIX A SE-135 REVISION HISTORY

MANUAL	MANUAL	PRODUCT REVISION
RELEASE DATE	REVISION	(REVISION NUMBER ON PRODUCT LABEL)
September 8, 2016	3-D-090816	
October 3, 2014	3-C-100314	04D
November 12, 2013	3-B-111213	— 04D
May 14, 2013	3-A-050613	

#### **MANUAL REVISION HISTORY**

#### **REVISION 3-D-090816**

#### SECTION 5

Added Figs. 14 and 15 RCM certification added.

#### **SECTION 6**

RCM certification added.

## **REVISION 3-C-100314**

#### **SECTION 4**

Figs. 7, 8, and 11 updated.

#### **REVISION 3-B-111213**

#### SECTION 2

Maximum trailing cable length added.

#### **SECTION 5**

Additional termination assembly and compliance specifications added.

#### **REVISION 3-A-050613**

#### **SECTION 2**

Network communications added.

#### **SECTION 4**

Ferrite placement instructions added.

#### **SECTION 5**

CE specifications, XGC option, SE-CS40-6 specifications and dimensions added.

#### SECTION 6

Ordering information updated.

### **PRODUCT REVISION HISTORY**

#### **REVISION 04D**

Ferrite kit added.





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